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Modeling and Forecast of Stock Prices for Several Banks in ISE

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**BİST'teki Bazı Bankalar için Hisse Senedi Fiyatı Modellemesi ve
Tahmini**

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SUMMARY

In recent years, forecasting is becoming more and more important for investment strategies. Before doing forecast, data must be prepared for forecasting by analyzing and modeling with suitable models. While volatility is seen mostly in financial data, the model used for forecasting must calculate the volatility factor. Academic researches show that ARCH/GARCH models with ARMA calculations give better results for volatility modeling.

In [1], volatility is modeled with different types of ARCH/GARCH models for XU100 daily data and GARCH model gives better results. On the other side, Switching ARCH (SWARCH) is found more suitable for weekly closing of XU100 index in [2]. And in [3], while EGARCH is used for US Dollar, TARCH is a better model for Euro currencies.

In this thesis, we concentrate to make an application of forecast of stock prices for one month, by using 2003-2012 daily closing of stock price of four banks, AKBANK (AK BANK), GARAN (GARANTİ BANK), ISCTR (İŞ BANK) and YKBANK (YAPI – KREDİ BANK). Firstly, theoretical background was given according to academic literature. After that, application part was started. A demo version of E-views, which is a statistical package, was used. Data of four banks were analyzed and modeled separately. Akaike Information Criteria (AIC) and Bayesian (Schwarz) Information Criteria (BIC) were considered while deciding to the model. AR(1) and EGARCH(1,1,1) models had the smallest Akaike Information Criteria and Bayesian Information Criteria values. So, these models were used for modeling the data.

Forecast was done after best model had been reached. At first, last five days were selected as forecast sample and five forecast values were obtained. These five forecast value were added to the end of the modeled data and then all data was modeled and forecasted again. This process was repeated three times and 20 forecast values were obtained for January 2013. Finally, these obtained forecast values were compared with real data of January 2013. All these applications were showed with graphs and tables.

ÖZET

Son yıllarda, yatırım stratejileri için, öngörü giderek daha önemli olmaktadır. Öngörü yapmadan önce, veriler analiz edilerek ve modellenerek öngörü için hazırlanmalıdır. Volatilite en çok finansal verilerde görüldüğünden, öngörü için kullanılan model öngörü faktörünü hesaba katmalıdır. Akademik araştırmalar ARMA hesaplamalı ARCH/GARCH modellerinin volatilitiyi modellemede daha iyi sonuçlar verdiğini göstermektedir.

[1]'de volatilité, İMKB100 günlük verileri için farklı türdeki ARCH/GARCH modelleriyle modellenmiş ve GARCH modeli daha iyi sonuç vermiştir. Diğer yandan, [2]'de Switching ARCH (SWARCH) modeli İMKB100 endeks haftalık kapanış verileri için daha uygun bulunmuştur. [3]'de, EGARCH modeli ABD Doları için kullanılırken, TARARCH Euro için daha iyi bir model olmuştur.

Biz bu tezde, dört bankanın, AKBANK (AK BANK), GARANTİ BANKASI, İŞBANKASI (İŞ BANKASI) ve YKBBANK (YAPI – KREDİ BANKASI), 2003 – 2012 günlük kapanış hisse senedi fiyatlarını kullanarak, bir aylık öngörü uygulaması yaptık. Öncelikle, akademik literature göre teorik altyapı verildi. Daha sonra uygulama kısmı başladı. Bir istatistiksel paket olan E-views'un demo versiyonu kullanıldı. Dört bankanın verileri ayrı ayrı analiz edildi ve modellendi. Modele karar verirken Akaike Bilgi Kriteri (AIC) ve Bayezyen (Schwarz) Bilgi Kriteri (BIC) göz önüne alındı. AR(1) ve EGARCH(1,1,1) modelleri en küçük Akaike Bilgi Kriteri ve Bayezyen Bilgi Kriteri değerlerine sahiptir. Bu yüzden verileri modellemek için bu modeller kullanıldı.

En iyi model elde edildikten sonra öngörü yapıldı. Öncelikle son beş gün öngörü aralığı olarak seçildi ve beş öngörü değeri elde edildi. Bu beş öngörü değeri, modellenmiş verilerin altına eklendi ve bütün veriler tekrar modellendi ve öngör yapıldı. Bu süreç üç kez tekrar edildi ve Ocak 2013 için 20 öngörü değeri elde edildi. Sonuçta, elde edilen bu değerler Ocak 2013'ün gerçek değerleriyle karşılaştırıldı. Bütün bu uygulamalar grafikler ve tablolarla gösterildi.

INTRODUCTION

Forecasting for stock prices is the process of estimation about future values of stock certificates. Making Forecasting by using suitable mathematical models is very important for investment strategies. Good forecast depends on a good model. Stochastic and deterministic parts of data must be analyzed as good as possible while trying to define a good model.

Forecasting can be done according to model that used when modeling the data. These models, called Autoregressive (AR) Model, Moving Average (MA) Model and the combination of these two models, Autoregressive Moving Average (ARMA) Model, utilized according to the correlogram of the data. If the data has volatility, AR models gives better results when forecasted.

There are many academical researchs about forecasting of financial and stock price data. According to many researchs, most of financial data (financial data include stock price data.) have volatility. In literature financial data with volatility are forecasted by using ARCH, GARCH, EGARCH, TARCH models.

In [1], it can be seen a large application of ARCH, GARCH, EGARCH, TARCH models with ARMA calculations to XU100 daily data. This application is used to analyzed valuation and forecast capacity of ARCH model and its types. This article shows that GARCH and ARMA models are successful for modeling volatility.

Volatility of XU100 index weekly closing data is forecasted with ARCH, GARCH and Switching ARCH (SWARCH) models in [2]. According to empirical results of the application, performance of alternative forecast models are compared and this search says that SWARCH model gives better results than ARCH and GARCH models for this data.

In [3], return series of foreign currencies are forecasted with ARCH models. In this article, US Dollar and Euro prices are used for the application part. After applying different types of ARCH models to the data, the best solution for US Dollar is found at AR and EGARCH models and Euro has the best result at AR and TARCH models.

The objective of this thesis is to evaluate future stock price of AK BANK (AKBNK), GARANTI BANK (GARAN), IS BANK (ISCTR), YAPI-KREDİ BANK (YKBNK) in ISE by modeling historical data with GARCH models. Historical daily closing stock price values of these four banks for ten years are used for the application part. If there will be a good and clear result then successful investment can be attained about the four Banks in ISE.

In second section, we give fundamental information about theoretical background of volatility and modeling. In third section, forecast methods are introduced. In fourth section, our data is presented, compared, modeled and forecasted and the graphs of these applications are given. In fifth section, we give the conclusion of the thesis.

2. THEORITICAL BACKGROUND

2.1. Volatility

Volatility means the spread of all probably results of an uncertain variable. Especially, in financial markets, we are often faced with the spread of entity returns. Statistically, volatility is often calculated like standard deviation

$$\sigma' = \sqrt{\frac{1}{T-1} \sum_{t=1}^T (r_t - \mu)^2}$$

where r_t is the return on day t , and μ is the average return over the T –day period.

Sometimes, variance, σ^2 , is used to calculate volatility. Since variance is the square of standard deviation, it does not matter which one is used for comparing the volatility of two assets. However, variance is much less stable and less admirable than standard deviation and it is not good for using computer prediction and volatility forecast evaluation. Furthermore, standard deviation is expressed in the same unit of measure like mean, so variance is expressed in the square of that unit. Therefore, standard deviation is more suitable and intuitive for volatility measuring. [4]

2.1.1. Historical Volatility

The historical volatility is the volatility of a stock prices obtained from the historical prices of a special stock. As it said above, the mostly used way is standard deviation. Therefore, the historical volatility is estimated as

$$\sigma = \sqrt{\frac{1}{n-1} \sum_{i=1}^n (u_i - \bar{u})^2}$$

where \bar{u} is defined by

$$\bar{u} = 1/n \sum_{j=1}^n u_j$$

σ gives the estimated volatility per interval. Volatility is generally expressed in annual terms to do it independent from the interval lengths. To do this, estimation is measured with an annualization factor (make normal constant) h , the number of intervals per annum such that

$$\sigma_{an} = \sigma * \sqrt{h}$$

2.1.2. Implied Volatility

An option pricing model (like the *Black & Scholes* model) gives a theoretical price for an option as a function of the exact parameters — constant volatility being one. However, if the option is traded, the market price might be different from the model price. In that case it may be asked that, which volatility estimate should be used in the model so that the model price and the market price are the same? This is the implied volatility. In a constant volatility construction, implied volatility is the volatility of the underlying asset price that is definite in the market price of an option according to a specific model. [5]

2.2. Augmented Dickey-Fuller Unit Root Tests

Augmented Dickey-Fuller t-statistic is used for deciding to difference time series to make it stationary.

If the time series is stationary (i.e. doesn't have a trend) and tends to slow-turning around zero, the following test equation can be used:

$$\Delta z_t = \theta z_{t-1} + \alpha_1 \Delta z_{t-1} + \alpha_2 \Delta z_{t-2} + \dots + \alpha_p \Delta z_{t-p} + a_t$$

where the number of augmenting lags (p) is determined by minimizing the Schwartz Bayesian information criterion or minimizing the Akaike information criterion or lags are dismissed until the last lag is statistically meaningful. The t-statistic combined with the ordinary least squares estimate of θ , is used for the test and it is called the Dickey-Fuller t-statistics. The Dickey-Fuller t-statistic does not follow a standard t-distribution as the sampling distribution of this test statistic is skewed to

the left with a long, left-hand-tail. The test is left-tailed. The null hypothesis of the Augmented Dickey-Fuller t-test is

$$H_0 : \theta = 0 \quad (\text{i.e. the data must be differenced to be stationary})$$

versus the alternative hypothesis of

$$H_1 : \theta < 0 \quad (\text{i.e. the data is trend stationary and does not need to be differenced})$$

If the time series is stationary and tends to slow-turning around a non-zero value, the following test equation can be used:

$$\Delta z_t = \alpha_0 + \theta z_{t-1} + \alpha_1 \Delta z_{t-1} + \alpha_2 \Delta z_{t-2} + \dots + \alpha_p \Delta z_{t-p} + a_t$$

This equation is suitable for time series which has an intercept term but no time trend. Again the number of augmenting lags (p) is determined by minimizing the Schwartz Bayesian information criterion or minimizing the Akaike information criterion or lags are dismissed until the last lag is statistically meaningful. The t-statistic may be used on the θ coefficient to decide whether data should be differenced to be stationary or not. The test is left-tailed. The null hypothesis of the Augmented Dickey-Fuller t-test is

$$H_0 : \theta = 0 \quad (\text{i.e. the data should be differenced to be stationary})$$

versus the alternative hypothesis of

$$H_1 : \theta < 0 \quad (\text{i.e. the data is trend stationary and does not need to be differenced})$$

If the time series has an upward or downward trend in it and tends to slow-turning around a trend line you would draw through the data, the following test equation can be used :

$$\Delta z_t = \alpha_0 + \theta z_{t-1} + \gamma t + \alpha_1 \Delta z_{t-1} + \alpha_2 \Delta z_{t-2} + \dots + \alpha_p \Delta z_{t-p} + a_t$$

This equation has an intercept term and a time trend. Again, the number of augmenting lags (p) is determined by minimizing the Schwartz Bayesian information criterion or minimizing the Akaike information criterion or lags are dismissed until the last lag is statistically meaningful. The t-statistic may be used on the θ coefficient to decide whether data should be differenced to be stationary or a time trend is needed to put in the regression model to correct for the variables deterministic trend. The test is left-tailed.

The null hypothesis of the Augmented Dickey-Fuller t-test is

$$H_0 : \theta = 0 \quad (\text{i.e. the data should be differenced to be stationary})$$

versus the alternative hypothesis of

$$H_1 : \theta < 0 \quad (\text{i.e. the data is trend stationary and needs to be analyzed by means of using a time trend in the regression model instead of differencing the data}) [6]$$

2.3. AR & MA Models

2.3.1. Autoregressive Model

One of the most commonly used way for modeling time series is the AR model. The background of this model is that the observed time series X_t depends on a weighted linear sum of the past values, p , of X_t and a random shock ε_t . Therefore, the name “autoregressive” comes from this idea.

Technically, AR(p) model can be formulated by the following equation:

$$X_t = \phi_1 X_{t-1} + \phi_2 X_{t-2} + \dots + \phi_p X_{t-p} + \varepsilon_t,$$

where X_t shows the time-series and ε_t implies a white-noise process. The value of p is called the order of the AR model. If $p = \infty$ then the process is called infinite AR process.

So, an autoregressive model means a linear regression of the current value of the series against one or more previous values of the series. Therefore the model might be compared with other methods with the standard linear least squares technique, where the resulting estimation of the parameters, ϕ_p , has a straight forward interpretation.

Often in the literature, AR(p) model is expressed with the lag operator, L , which is defined as

$$LX_t = X_{t-1}$$

Consequently $L(LX_t) = L^2X_t = X_{t-2}$ and therefore in general $L^sX_t = X_{t-s}$ and $L^0X_t = X_t$ this means operating L on a constant leaves the constant unaffected. With the lag operator, an AR(1) model $X_t = \phi X_{t-1} + \varepsilon_t$ can be showed in the following way:

$$X_t = \phi X_{t-1} + \varepsilon_t \Leftrightarrow X_t(1 - \phi L) = \varepsilon_t$$

Similarly, a general form of the AR(p) model is

$$X_t = \phi_1 X_{t-1} + \phi_2 X_{t-2} + \cdots + \phi_p X_{t-p} + \varepsilon_t,$$

or, with the lag operator:

$$X_t = \phi_1 L X_t + \phi_2 L^2 X_t + \cdots + \phi_p L^p X_t + \varepsilon_t$$

$$X_t = X_t(\phi_1 L + \phi_2 L^2 + \cdots + \phi_p L^p) + \varepsilon_t$$

$$X_t(1 - \phi_1 L + \phi_2 L^2 + \cdots + \phi_p L^p) = \varepsilon_t$$

in the brief form: $X_t \Phi(L) = \varepsilon_t$, where $\Phi(L)$ is a polynomial of order p in the lag operator:

$$\Phi(L) = 1 - \phi_1 L + \phi_2 L^2 + \cdots + \phi_p L^p$$

2.3.2. Moving Average Model

Another most commonly used way for modeling time-series is the MA model. The background of this model is that the observed time-series X_t depends on a weighted linear sum of past, q , random shocks. This means that at period t a random shock ε_t is activated and this random shock is independent of random shocks of other periods. The observed time-series X_t is then generated by a weighted average of current past shocks – so the name of model is “moving average”.

Technically, MA(q) model can be expressed with the following equation:

$$X_t = \varepsilon_t + \theta_1 \varepsilon_{t-1} + \cdots + \theta_q \varepsilon_{t-q},$$

where X_t is the time-series and ε_{t-q} implies to a white-noise process. The value of q is called the order of the MA model. If $q=\infty$ then the process is called infinite MA process.

So a MA model means a linear regression of the current value of the series against the random shocks of one or more previous values of the series. Since moving average model is based on the unobservable error terms, fitting a moving average model is more complicated than fitting an autoregressive model. Therefore in opposite to an AR model, iterative non-linear fitting process has to be utilized and the resulting estimation of the parameters has a less obvious comment than in the case of AR models.

As before, MA model is also can be expressed with the lag operator in the following way:

$$X_t = \theta(L) \varepsilon_t,$$

where $\theta(L)$ is a polynomial of order q in the lag operator

$$\theta(L) = 1 + \theta_1 L + \theta_2 L^2 + \dots + \theta_q L^q.$$

2.3.3. Autoregressive Moving Average (ARMA) Model

Box and Jenkins (1970) developed a systematic methodology for combining two processes which were given below and originally investigated by Yule. An ARMA model occur from his name of two components: the weighted sum of past values (autoregressive component) and the weighted sum of past errors (moving average component). An ARMA model of order (p,q) can be expressed as in the following equation:

$$X_t = \phi_1 X_{t-1} + \phi_2 X_{t-2} + \dots + \phi_p X_{t-p} + \varepsilon_t + \theta_1 \varepsilon_{t-1} + \dots + \theta_q \varepsilon_{t-q}$$

Since both AR and MA models are stationary, the ARMA process is also stationary, if the roots of the polynomial $\phi(z) = 0$ lie outside unit circle. This is the only condition, as every MA(q) process is stationary. In contrast, an ARMA process is called invertible, if the roots of $\theta(z) = 0$ lie outside the unit circle, this is the only condition as every AR(p) process is invertible. [7]

2.4. ARCH, GARCH & EGARCH Models

2.4.1. Autoregressive Conditional Heteroscedasticity Model

The autoregressive conditional heteroscedasticity is utilized for modeling financial time series. It is presented by Robert F. Engle in 1982.

Consider the following simple scalar model

$$y_t = \mu + e^t, t = 1, \dots, T$$

$$e^t = z_t \sigma_t$$

$$\sigma_t^2 = \omega + \sum_{i=1}^q \alpha_i e_{t-i}^2 = \omega + a(L) e_t^2$$

where $\alpha_1, \dots, \alpha_q, \mu$ and ω are scalar parameters to be predicted. z_t is thought to have mean zero and variance one, and is often (but not always) supposed to be normally

distributed. ω and α_i have to be assumed all positive for obtaining positive values for the estimate of the condition variance.

2.4.2. Generalized Autoregressive Conditional Heteroscedasticity Model

Generalized autoregressive conditional heteroscedasticity model is presented by Tim Bollerslev (1986). It is an upper version of autoregressive conditional heteroscedasticity model.

Let the $e_t = \sigma_t$ as before, but now let

$$\sigma_t^2 = \omega + \sum_{i=1}^p \beta_i \sigma_{t-i}^2 + \sum_{i=1}^q \alpha_i e_{t-i}^2$$

which is a natural generalization corresponding to an ARMA model for the variance. This model is called a GARCH(p,q) model. Also in the GARCH model, parameters must be restricted to be positive, which guarantees a positive prediction of the conditional variance. More compactly;

$$\sigma_t^2 = \omega + b(L)\sigma_t^2 + a(L)e_t^2$$

If the variance process follows the equivalent of an ARIMA model, allowing for unit roots in the lag polynomials, in that case where

$$\alpha_1 + \dots + \alpha_q + \beta_1 + \dots + \beta_p = 1$$

they refer to the model as an IGARCH(p,q) model.

2.4.3. Exponential Autoregressive Conditional Heteroscedasticity

Model

A constraint of the GARCH models is that it limits the shocks to the model to have the same effect on the conditional variance whether the shocks are negative or positive. This may or may not be a reasonable assumption but it is testable. Since it rules out cyclic attitude in the conditional variance, the positivity constraints on the parameters can also be considered restrictive. For those reasons Nelson (1991) suggests the EGARCH(p,q) model:

$$\log(\sigma_t^2) = \omega + \sum_{i=1}^p \beta_i \log(\sigma_{t-i}^2) + \sum_{i=1}^q \alpha_i (\varphi z_{t-i} + \gamma [|z_{t-i}| - E|z_{t-i}|])$$

In the EGARCH the parameters do not have to be not positive. The term $|z_{t-i}| - E|z_{t-i}|$ is positive if the error term is larger than its expected value and negative otherwise. For $\log(\sigma_t^2)$, other models can also be used but for the specific model suggested by Nelson, he shows that the model seems to behave well asymptotically. [8]

3. FORECAST

According to Chatfield (2001), a forecasting method is described as in the following way: Let x_1, x_2, \dots, x_N be observations on a single time series and x_{N+h} values is going to be forecasted for $h=1,2,\dots$. Then the process of calculation a point forecast, $\hat{x}_N(h)$, which is based only on past and present values of the given series is called a forecasting method.

3.1. Model-Based Forecasting

Forecast will be calculated after having identified a particular model for the time series and predicted the model parameters, by using the fitted model (M denotes the true model, M_f fitted model). The best way to calculate a forecast is to choose $\hat{x}_N(h)$ to be the expected value of X_{N+h} conditional on the model, M , and on the information available at time N , which will be denoted by I_N :

$$\hat{x}_N(h) = E(X_{N+h} | M, I_N),$$

where I_N consists for a procedure of x_N, x_{N-1}, \dots plus the current value of time, namely N .

3.1.1. Linear Model: Autoregressive (AR) Models

The estimation is done as in the following equation:

One step forecast: $\hat{X}_{t-1}(1) = \tilde{\Phi}_1 X_{t-1} + \tilde{\Phi}_2 X_{t-2} + \dots + \tilde{\Phi}_p X_{t-p}$ where the true coefficients are replaced by in-sample estimates Φ_j

Two step forecast: $\hat{X}_{t-1}(2) = \tilde{\Phi}_1 \hat{X}_{t-1}(1) + \tilde{\Phi}_2 X_{t-1} + \dots + \tilde{\Phi}_p X_{t-p+1}$ where the unknown observation X_t is changed with its estimation $\hat{X}_{t-1}(1)$. For longer periods, predictions will converge to the long run mean which must be zero in the end.

Specifying AR models with a constant term:

$$X_t = \mu + \Phi_1 X_{t-1} + \dots + \Phi_p X_{t-p} + \varepsilon_t$$

And with a mean:

$$EX_t = \frac{\mu}{1 - \phi_1 - \dots - \phi_p} = \frac{\mu}{\phi(1)}$$

(Case of $\phi(1) = 0$ has been excluded)

3.1.2. Linear Model: Moving Average (MA) Models

Forecasting an MA model needs the prediction of the coefficients θ_j from the sample after having defined the lag order q . The visual inspection of correlograms or information criterias can be used for defining the lag order q . By maximizing the likelihood or by approximating computer algorithm predictions for coefficients θ_j can be obtained, but also predictions of the error terms ε_t have to be calculated with some computer algorithm.

One step forecast(if $\hat{\theta}_j$ and $\hat{\varepsilon}_t$ are available):

$$\hat{X}_{t-1}(1) = \hat{\theta}_1 \hat{\varepsilon}_{t-1} + \hat{\theta}_2 \hat{\varepsilon}_{t-2} + \dots + \hat{\theta}_q \hat{\varepsilon}_{t-q}$$

Two step forecast:

$$\hat{X}_{t-1}(2) = \hat{\theta}_2 \hat{\varepsilon}_{t-1} + \hat{\theta}_3 \hat{\varepsilon}_{t-2} + \dots + \hat{\theta}_q \hat{\varepsilon}_{t-q+1},$$

This means that some steps later, forecast values will be trivially zero.

3.1.3. Linear Model: Autoregressive Moving Average (ARMA) Models

Forecasting with parsimonious (parsimonious: representation with minimum number of free parameters) ARMA models could be exciting if it the sample is a small sample and some parameters set to zero while normally different from zero could lead to better predictions than models correctly including all parameters. Autocorrelation function and partial autocorrelation functions result is determined zero at a geometric rate for ARMA processes. To decide the lag orders p and q is difficult by looking to the visual inspection of correlograms and partial correlograms; therefore in the literature it is sometimes said to decide by considering the extended

versions of the correlogram (extended ACF, extended sample ACF) and most set lag order by information criteria.

One step forecast (if $\hat{\theta}_j$ and $\hat{\phi}_j$ are estimated, maximum likelihood approximated and approximate errors $\hat{\varepsilon}_t$ calculated):

$$\hat{X}_{t-1}(1) = \hat{\phi}_1 X_{t-1} + \dots + \hat{\phi}_p X_{t-p} + \hat{\theta}_1 \hat{\varepsilon}_{t-1} + \hat{\theta}_2 \hat{\varepsilon}_{t-2} + \dots + \hat{\theta}_q \hat{\varepsilon}_{t-q}$$

Two step forecasts:

$$\hat{X}_{t-2}(2) = \hat{\phi}_1 \hat{X}_t(1) + \hat{\phi}_2 X_{t-1} + \dots + \hat{\phi}_p X_{t-p} + \hat{\theta}_2 \hat{\varepsilon}_{t-1} + \dots + \hat{\theta}_q \hat{\varepsilon}_{t-q+1}$$

[7]

3.2 Static vs. Dynamic Forecasting

While doing forecasting, two different way can be used:

Dynamic version calculates forecasts for the periods after the first period by using the values which are the previously forecasted results of the lagged left-hand. These are also called n-step ahead forecasts.

Static version do the forecast with actual values rather than forecasted values (it can only be used when actual data are available). These are also called 1-step ahead or rolling forecasts. [12]

4. APPLICATION

4.1 DATA

For the application part, daily closing stock prices of four banks in ISE, which are AKBNK, GARAN, ISCTR and YKBNK are used. Stock prices graphs are drawn for each bank separately year by year.

Firstly, AKBNK' s daily closing stock prices are analyzed yearly and their graphs are given below.

AKBNK (AK BANK)

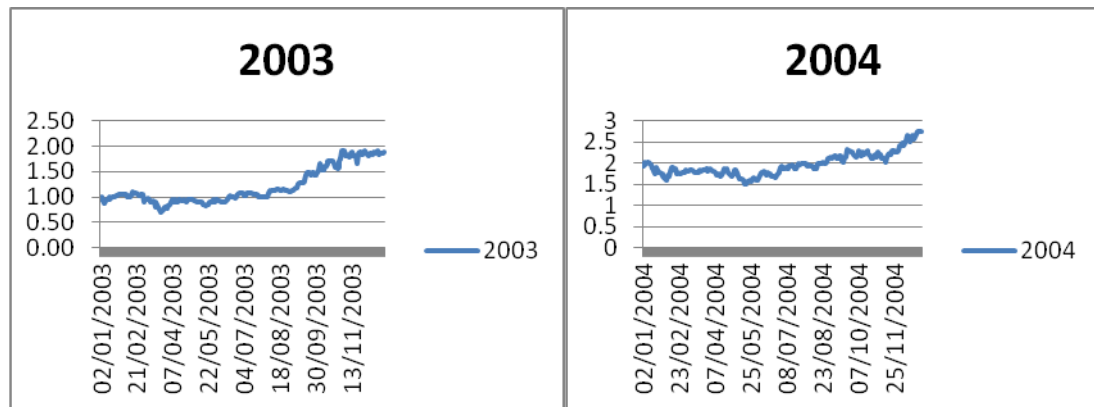


Figure 3.1 : AKBNK 2003 Stock Prices

Figure 3.2: AKBNK 2004 Stock Prices

When we look at the first two years, we can see the increase of stock prices. A trend would be seen at both years' graphs.

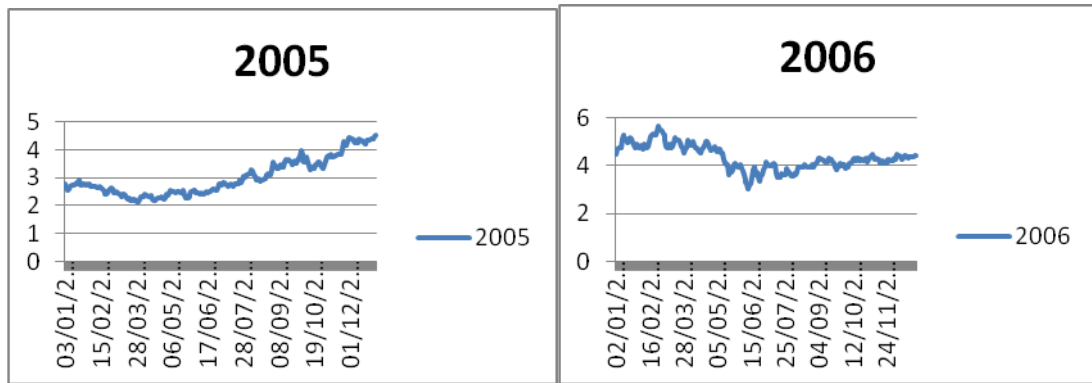


Figure 3.3 : AKBNK 2005 Stock Prices

Figure 3.4: AKBNK 2006 Stock Prices

At 2005's graph stock prices continue to rise. But in 2006 they are said to be decreased.

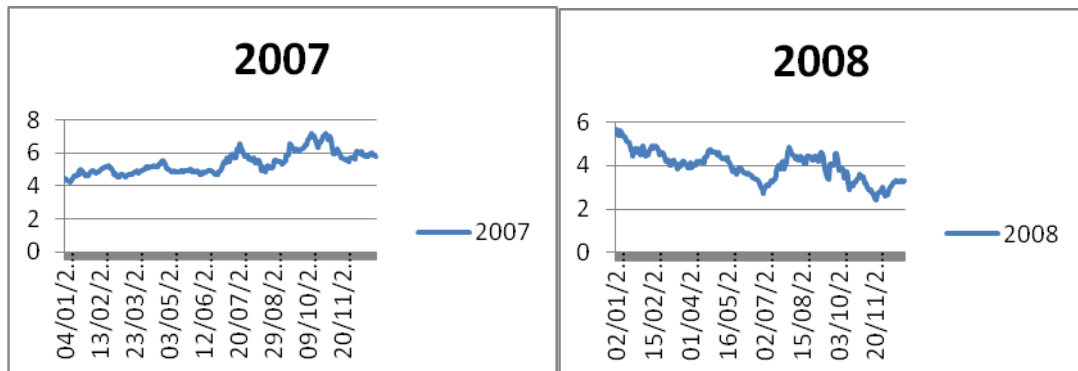


Figure 3.5 : AKBNK 2007 Stock Prices

Figure 3.6 : AKBNK 2008 Stock Prices

In 2007, prices again start to increase. But in 2008, they are seen to decrease again. This decrease may be caused by the economical crises which occurred in this year and affected nearly all the countries.

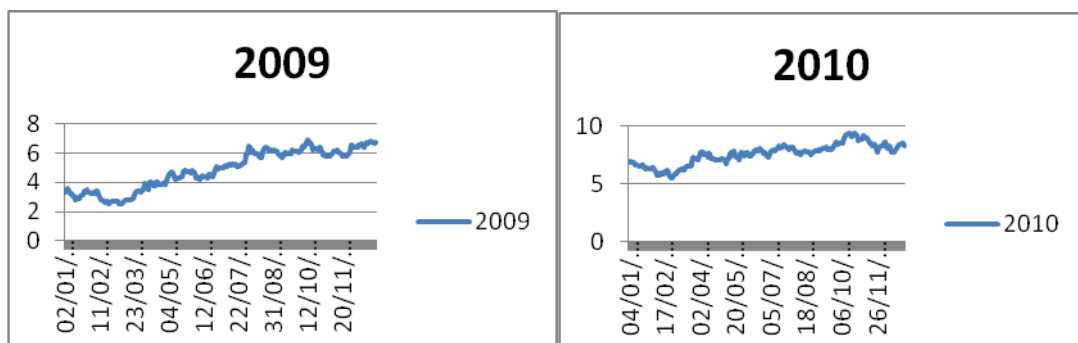


Figure 3.7 : AKBNK 2009 Stock Prices

Figure 3.8 : AKBNK 2010 Stock Prices

Effects of economical crises are seen to be eliminated in 2009. Prices increase after the first quarter of the year. The rise also can be seen in 2010 but increment range is not so wide.

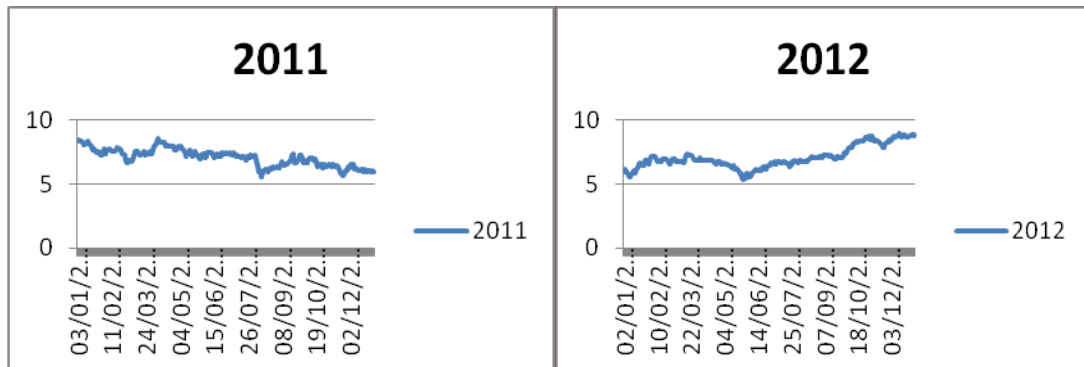


Figure 3.9 : AKBNK 2011 Stock Prices

Figure 3.10 : AKBNK 2012 Stock Prices

From the 2011's graph a slow decrease is seen. But in the last year the graph caught the trend again and the values rise nearly up to 2011's beginning values.



Figure 3.41: AKBNK 2003 – 2012 Stock Prices

When we look at the whole values, in some ranges a decline of stock prices can be seen. In a small part of 2006, in 2008 and in 2011 prices decrease more sharply than the other years. But in the whole perspective AKBNK's stock prices show upward trend and in 10 years prices become nine times larger than the beginning value.

GARAN (GARANTI BANK)

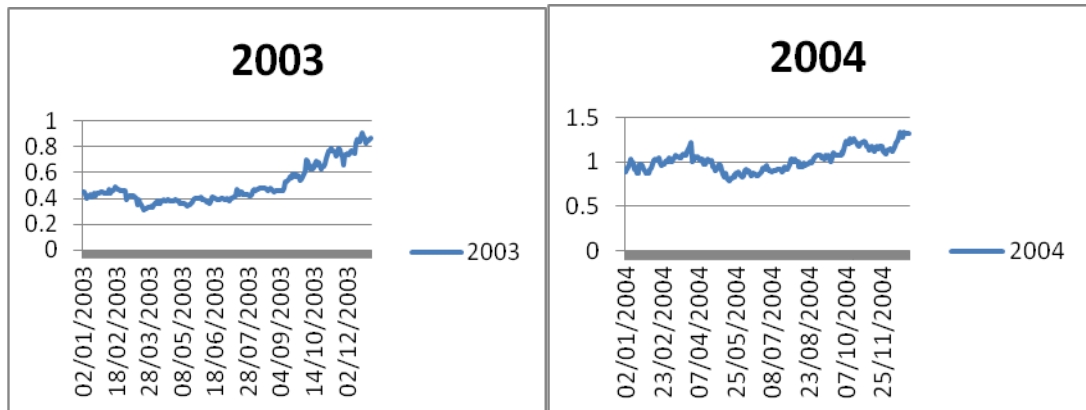


Figure 3.11: GARAN 2003 Stock Prices

Figure 3.12: GARAN 2004 Stock Prices

GARAN' s stock prices show a visible increase in the first year. But in the second year its increase become slower.

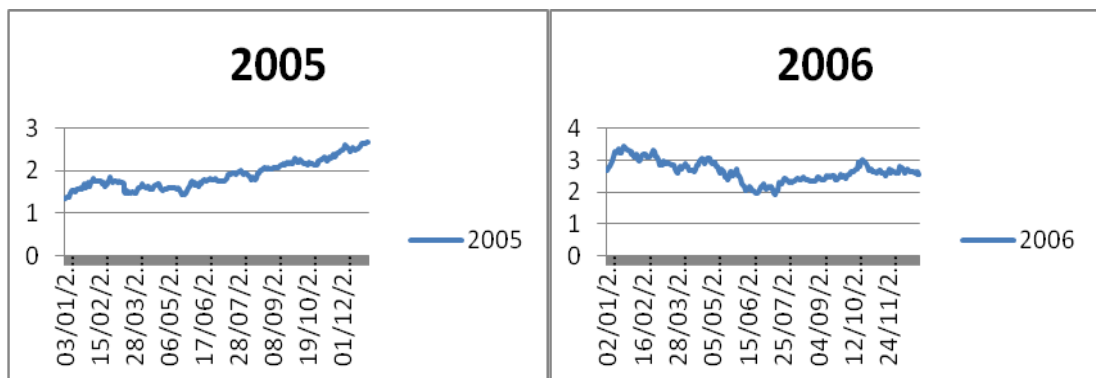


Figure 3.13: GARAN 2005 Stock Prices

Figure 3.14: GARAN 2006 Stock Prices

The rise also continues in 2005. But it turns down in 2006 and prices start to decrease.

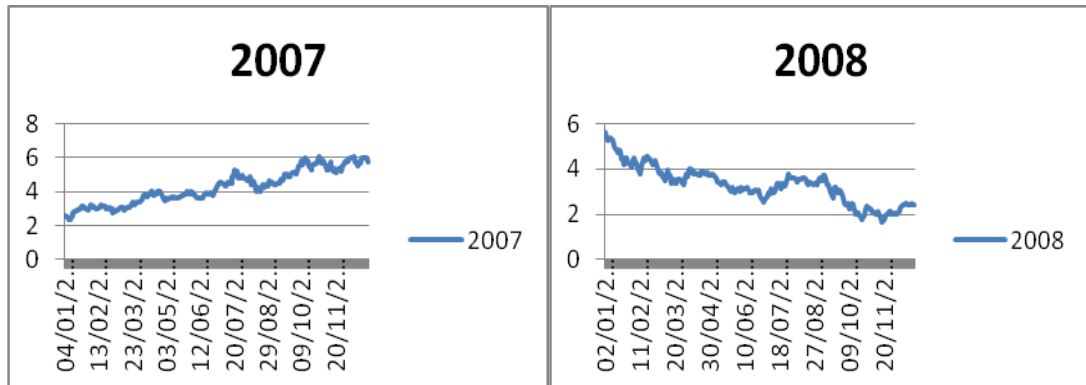


Figure 3.15: GARAN 2007 Stock Prices

Figure 3.16: GARAN 2008 Stock Prices

Although stock prices increase in 2007, the economical crise's negative effect is seen again in 2008's values.

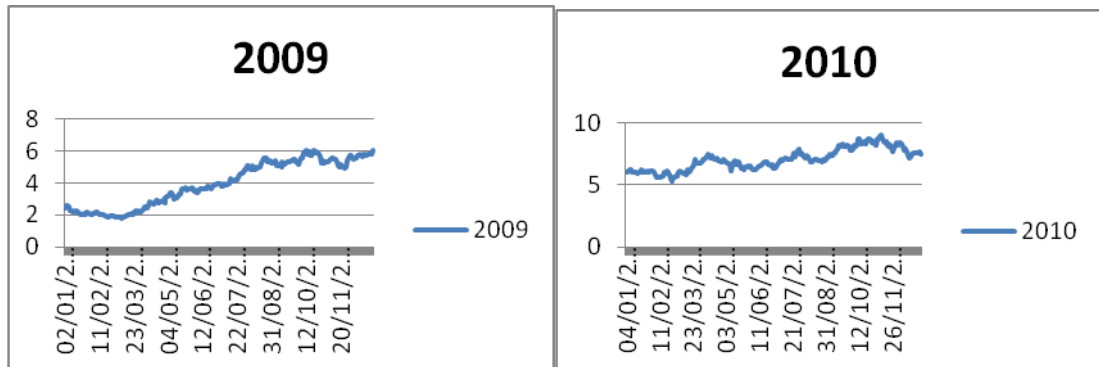


Figure 3.17: GARAN 2009 Graph

Figure 3.18: GARAN 2010 Graph

After 2008, GARAN gets over the effect of crises and its stock prices increase again along the 2009 and 2010.

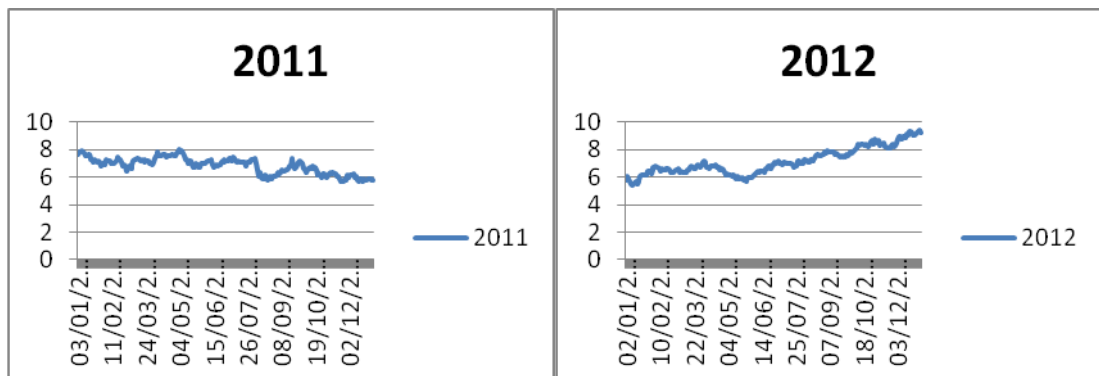


Figure 3.19: GARAN 2011 Stock Prices

Figure 3.20: GARAN 2012 Stock Prices

Though we see a slow decline in prices in 2011, in the last year GARAN also catch the upward trend as AKBNK.



Figure 3.42: GARAN 2003 - 2012 Stock Prices

The whole behavior of GARAN's stock prices seems to have an upward trend. In a part of 2006, in 2008 and in 2011 sharp declines can be seen. But GARAN increased its stock prices nearly ten times larger in 10 years.

ISCTR (IS BANK)

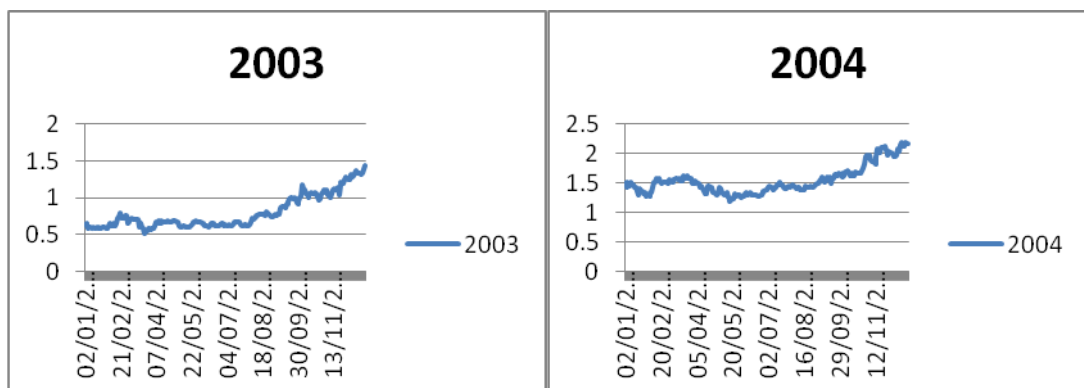


Figure 3.21: ISCTR 2003 Stock Prices

Figure 3.22: ISCTR 2004 Stock Prices

At the end of the first year, ISCTR stock prices became three times larger than the beginning of the year. The second year this increase continued slowly.

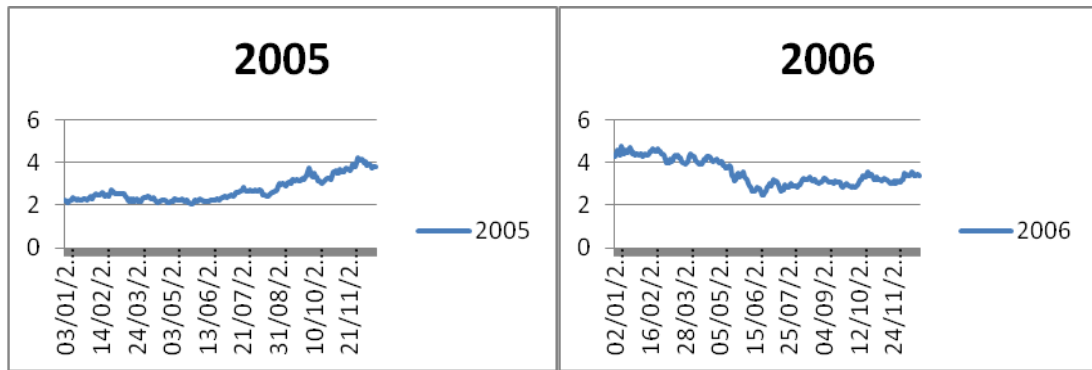


Figure 3.23: ISCTR 2005 Stock Prices

Figure 3.24: ISCTR 2006 Stock Prices

In 2005, prices also increase. But after the first quarter of the 2006, this increase turns down and at the end of the year, prices seem like the beginning of the year's values.

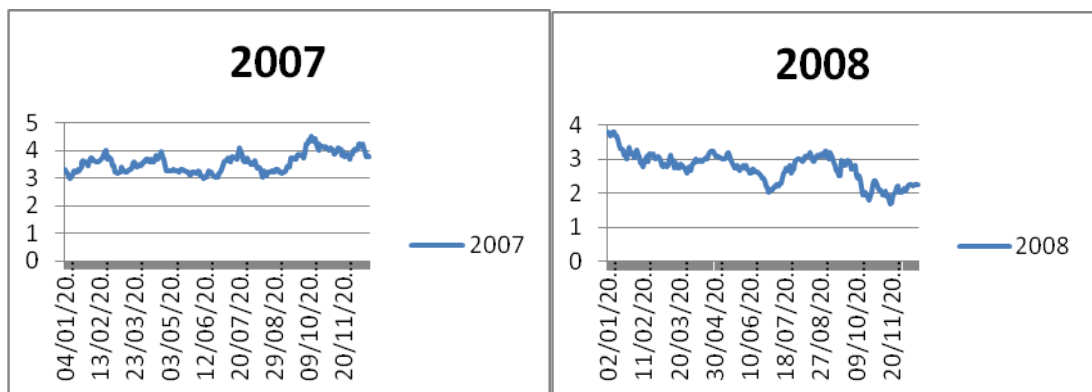


Figure 3.25: ISCTR 2007 Stock Prices

Figure 3.26: ISCTR 2008 Stock Prices

In 2007, stock prices rise up seasonally. After that year, in 2008, we again see the effect of economical crises. Along the year, stock prices lose their values nearly 50%.

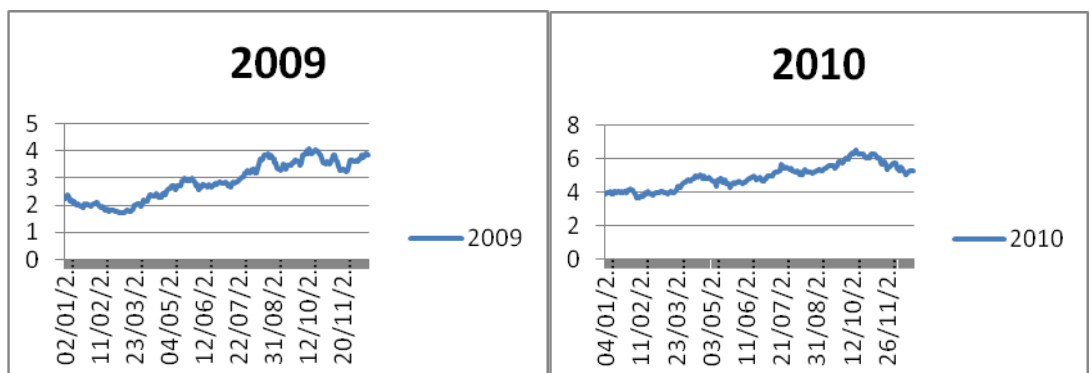


Figure 3.27: ISCTR 2009 Stock Prices

Figure 3.28: ISCTR 2010 Stock Prices

At the end of 2009, prices gain their 2008 beginning values and increase continues in 2010.

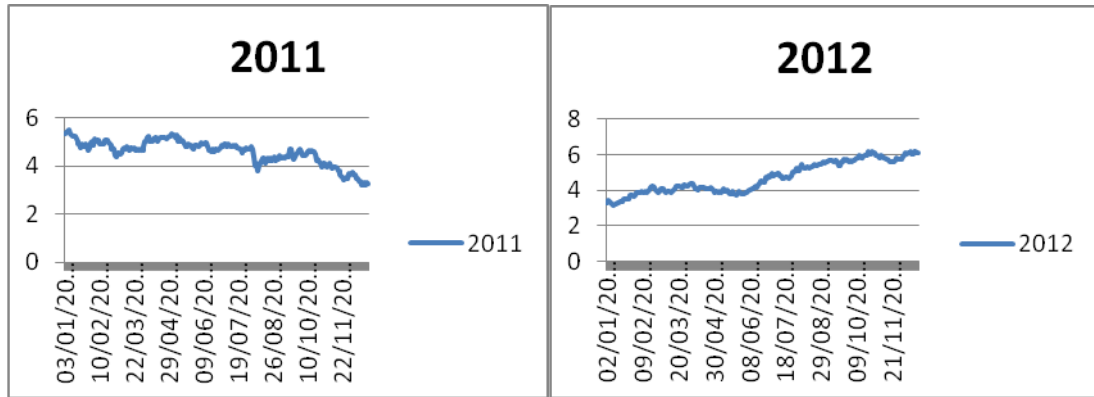


Figure 3.29: ISCTR 2011 Stock Prices

Figure 3.30: ISCTR 2012 Stock Prices

A slow decrease can be seen in 2011. However, in 2012 we see the top values İş Bank has ever had.



Figure 3.43: ISCTR 2003 - 2012 Stock Prices

In general perspective, except a part of 2006, all 2008 and 2011, ISCTR stock prices have a visible increase. Last values are six times larger than the beginning prices.

YKBNK (YAPIKREDI BANK)

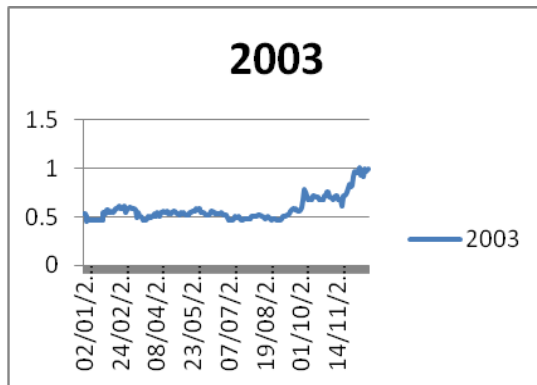


Figure 3.31: YKBNK 2003 Stock Prices

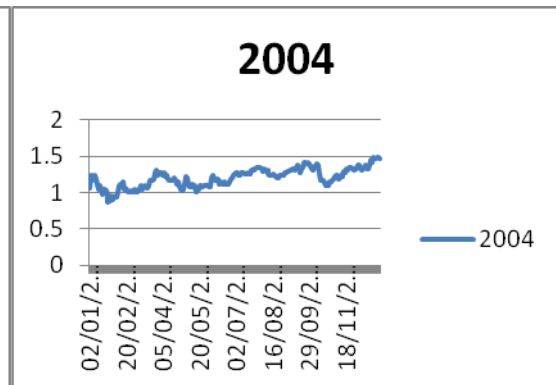


Figure 3.32: YKBNK 2004 Stock Prices

In the last quarter of 2003 YKBNK has a sharp increase, while in the first three quarter prices are nearly stable. In 2004, increase also continues but not as sharp as in 2003' last quarter.

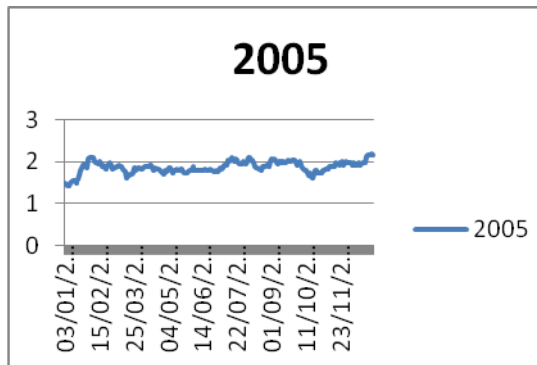


Figure 3.33: YKBNK 2005 Stock Prices

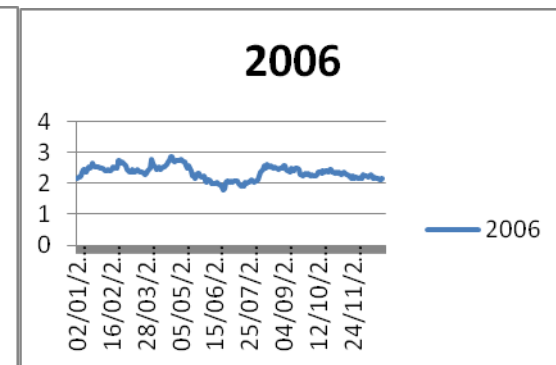


Figure 3.34: YKBNK 2006 Stock Prices

In 2005, prices increase in first month and then continues at the same level. In the first semi-year of 2006, prices also increase but in the second semi-year they decline to the 2006's beginning values.

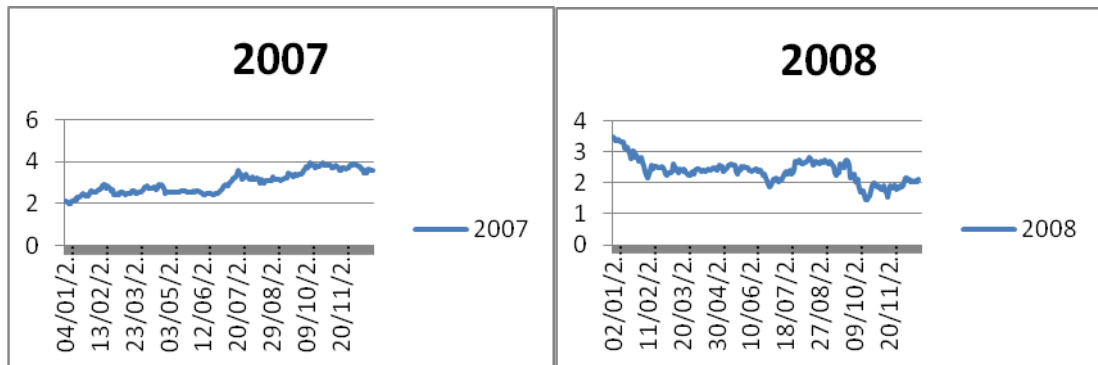


Figure 3.35: YKBNK 2007 Stock Prices

Figure 3.36: YKBNK 2008 Stock Prices

In 2007, prices has an upward trend and nearly 100% increase. After this year, we see the economical crise's effects on the stock prices and prices decrease.

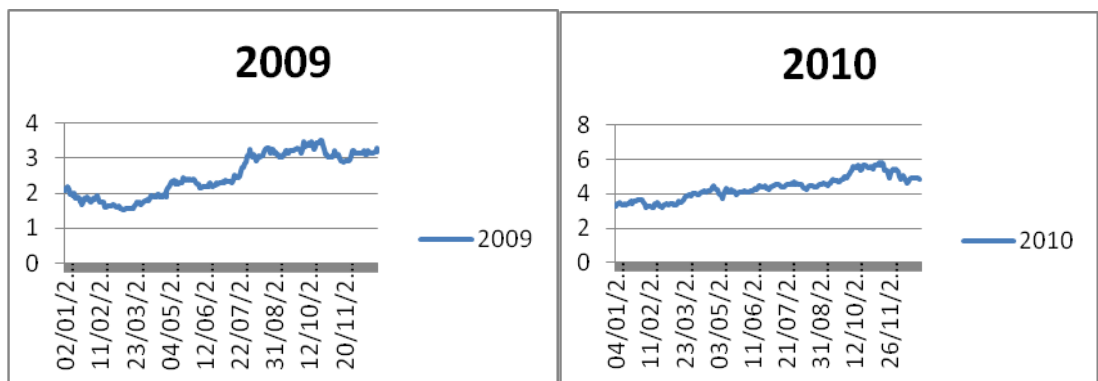


Figure 3.37: YKBNK 2009 Graph

Figure 3.38: YKBNK 2010 Graph

After crises year, we again see the upward trend in 2009 and 2010.

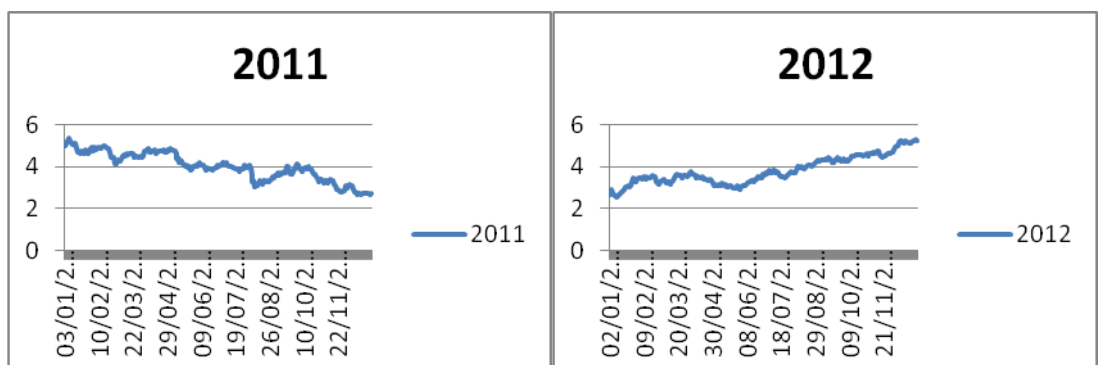


Figure 3.39: YKBNK 2011 Stock Prices

Figure 3.40: YKBNK 2012 Stock Prices

Upward trend turns down in 2011. But YKBNK stock prices catch an increase in the last year.



Figure 3.44: YKBNK 2003 – 2012 Stock Prices

Although we see decreases in a part of 2006, in 2008 and in 2011, in general YKBNK's stock prices has an upward trend through the past ten years. Prices have their top values in 2010 and in ten years, get nearly six times larger.

4.2 COMPARISON of BANKS BY YEARS FROM 2003 to 2012

2003

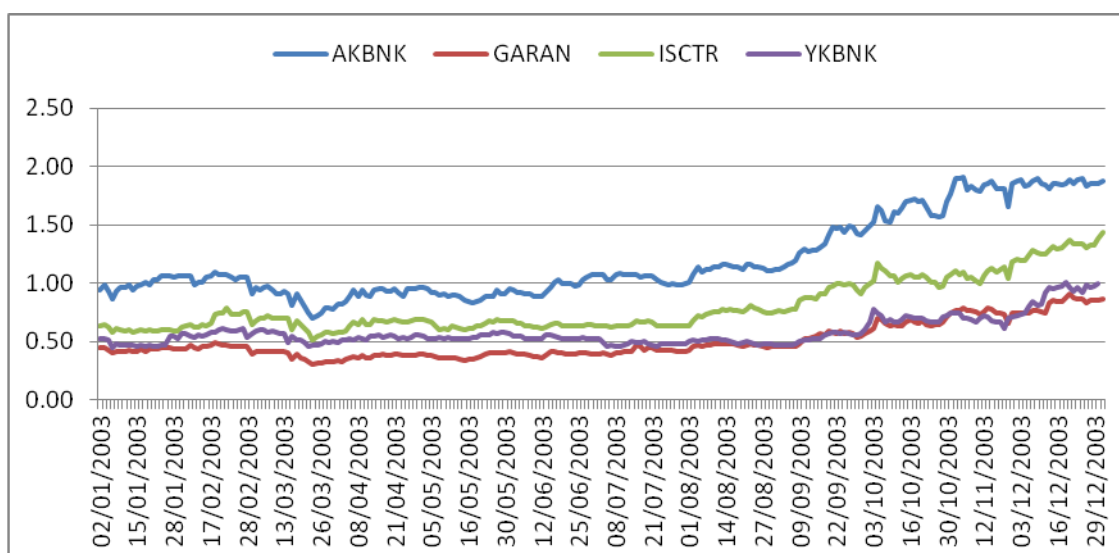


Figure 3.45: 2003 Stock Prices of Four Banks

At the first year, although all banks' stock prices are near, AKBNK seems more expensive than the others.

2004

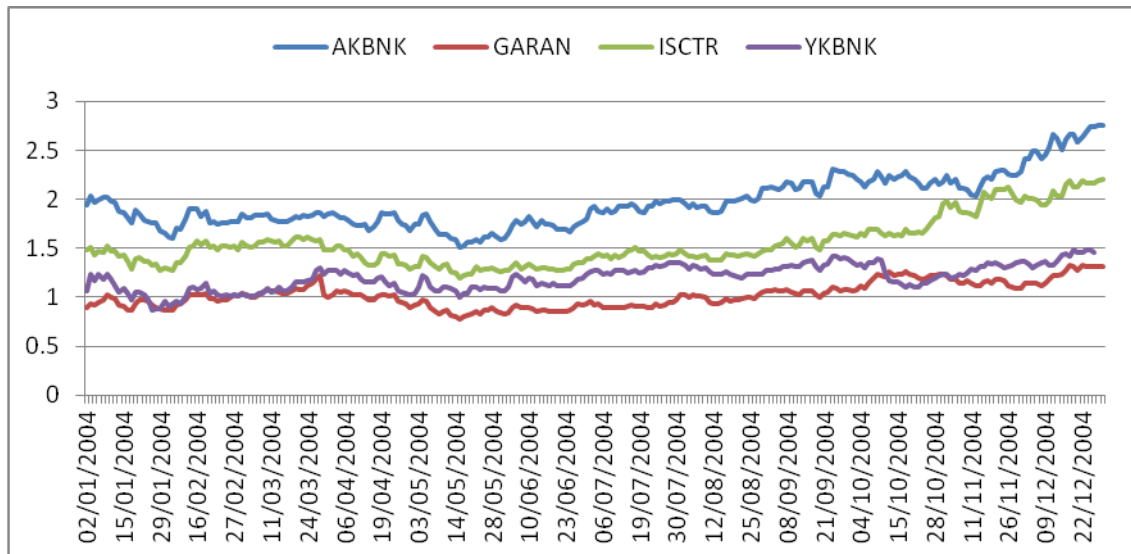


Figure 3.46: 2004 Stock Prices of Four Banks

ISBNK's stock prices come nearer to AKBNK. But AKBNK is still the most important stock price.

2005

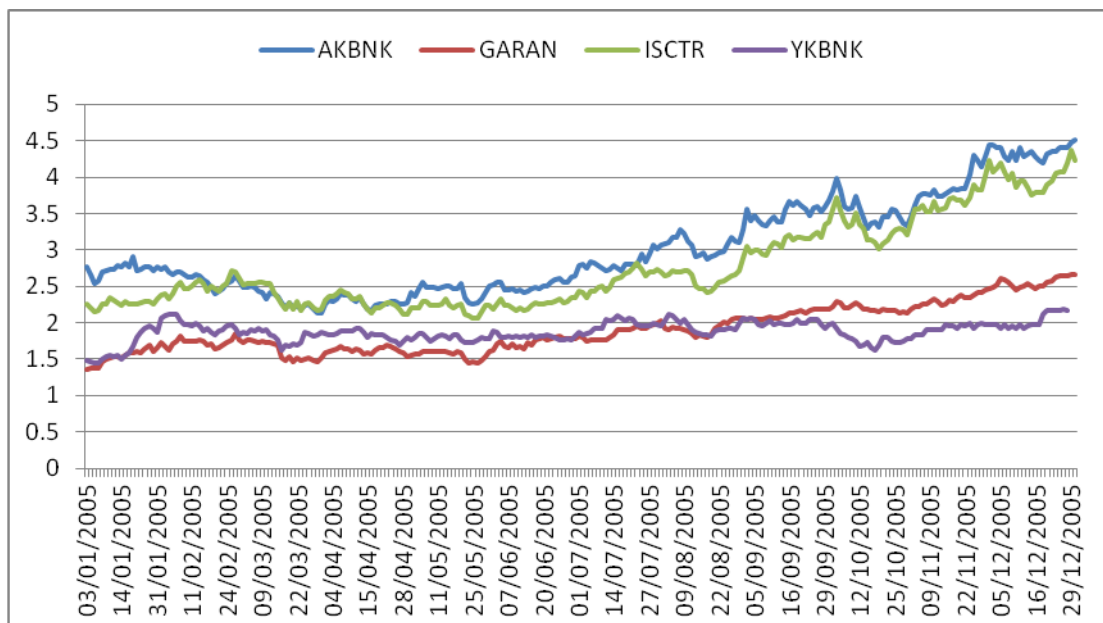


Figure 3.47: 2005 Stock Prices of Four Banks

In 2005, AKBNK and ISBNK behave nearly the same. On the other hand, GARAN and YKBNK go together.

2006

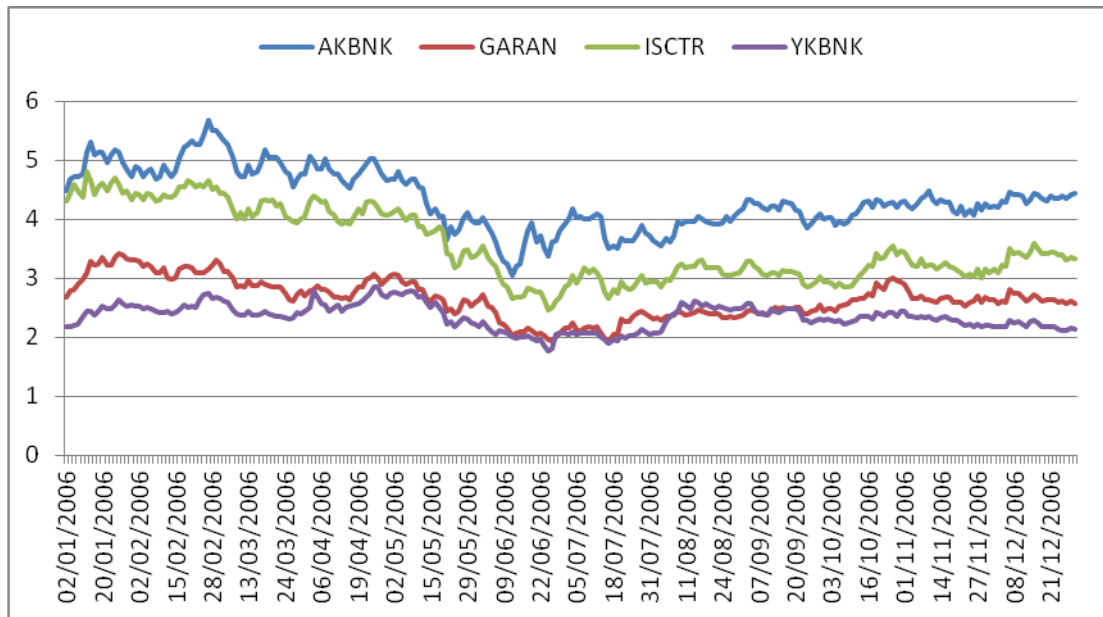


Figure 3.48: 2006 Stock Prices of Four Banks

The difference between AKBNK – ISCTR and GARAN - YKBNK is getting more.

2007

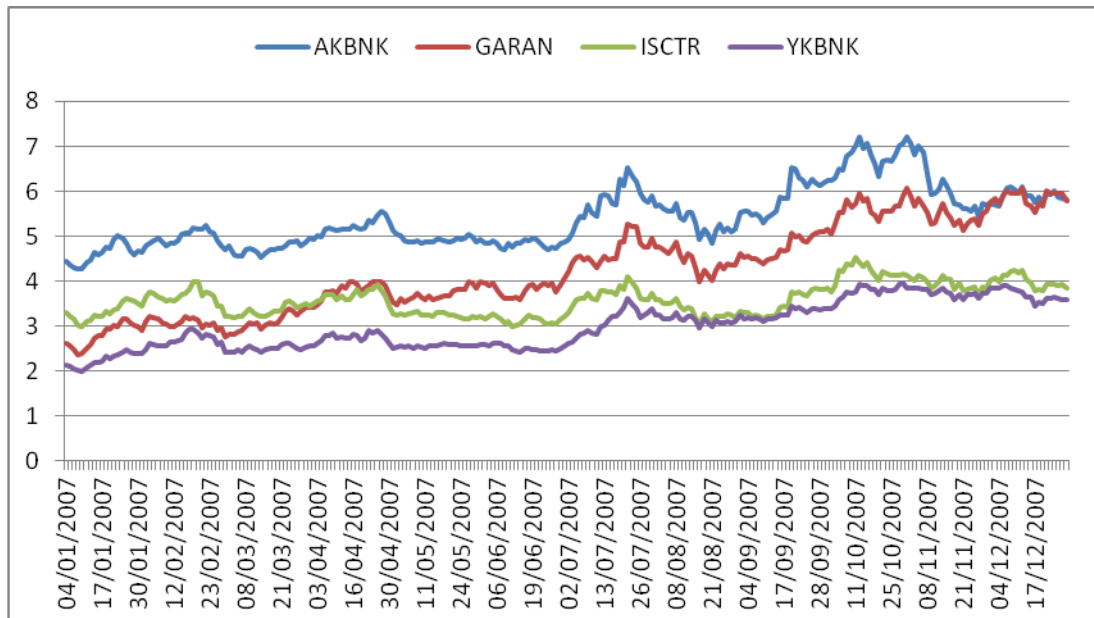


Figure 3.49: 2007 Stock Prices of Four Banks

In 2007, all stock prices behave the same, but they have differences between stock prices. AKBNK is still the most expensive stock price.

2008

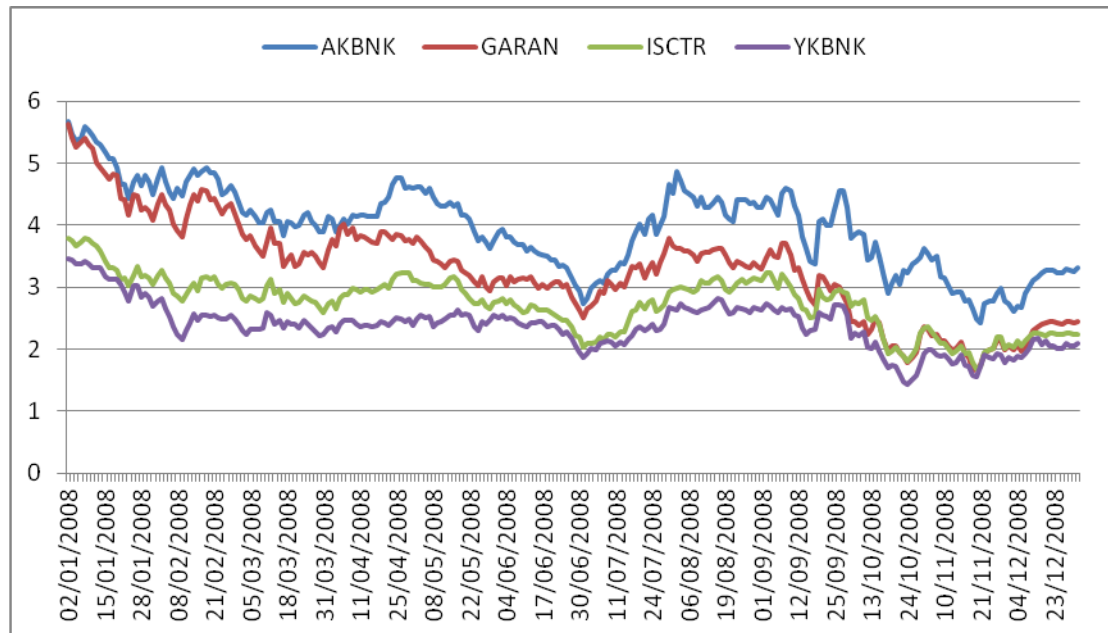


Figure 3.50: 2008 Stock Prices of Four Banks

GARAN's stock prices become more expensive than ISCTR. ISCTR behave like YKBNK. But in whole year, we see the crise's negative effect on each bank.

2009

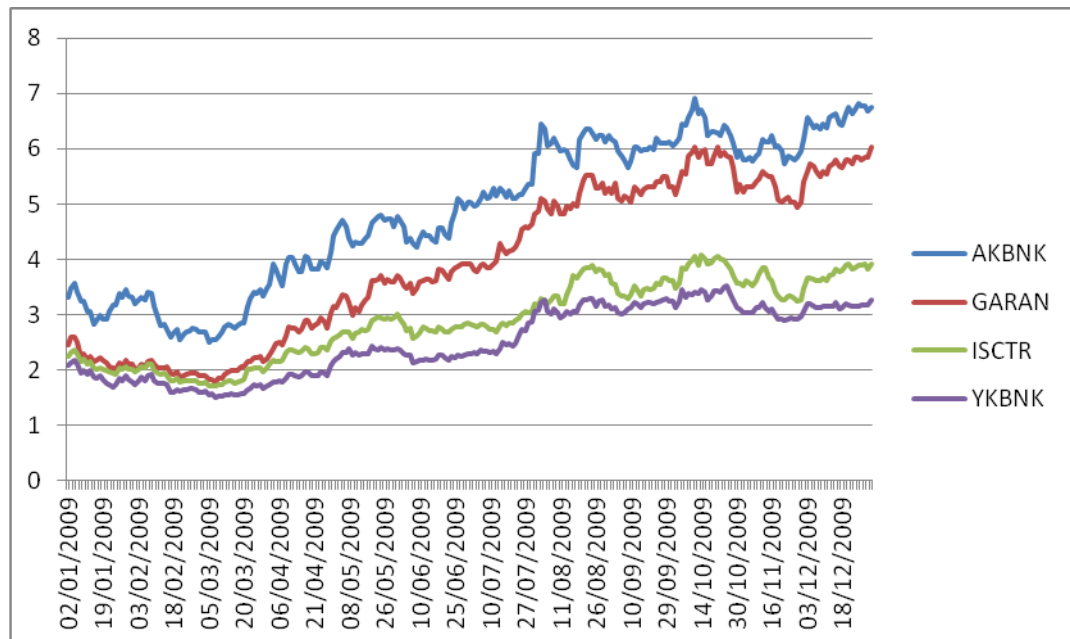


Figure 3.51: 2009 Stock Prices of Four Banks

At the beginning of the year, AKBNK is more expensive than the others. But GARAN's stock prices increase during the year and at the end, GARAN and AKBNK come closer.

2010

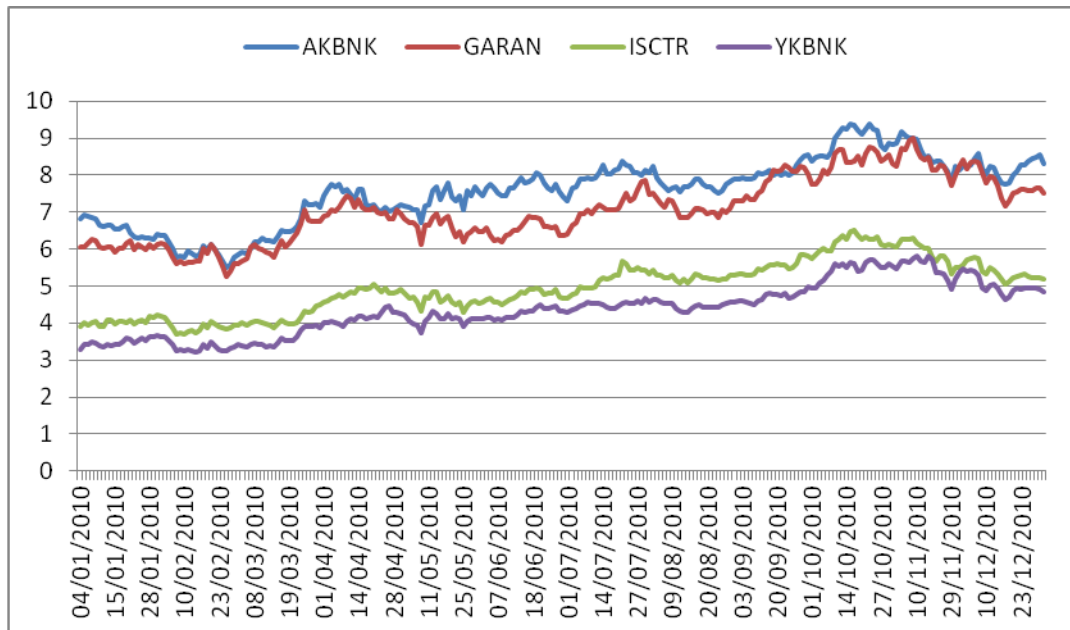


Figure 3.52: 2010 Stock Prices of Four Banks

In 2010, AKBNK – GARAN and ISCTR – YKBNK behave nearly the same again.

2011

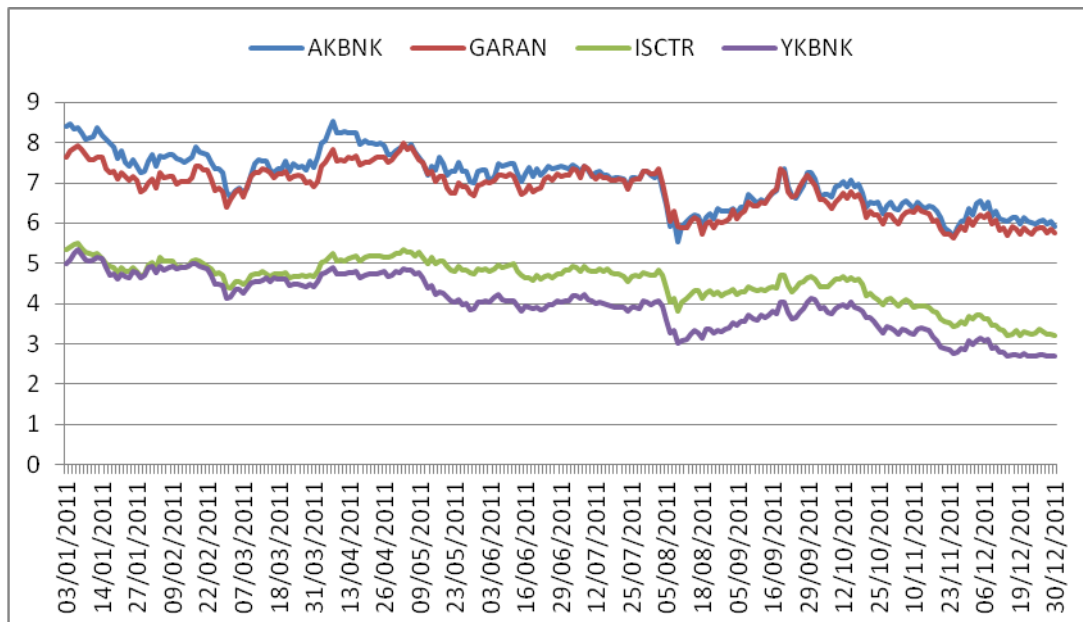


Figure 3.53: 2011 Stock Prices of Four Banks

Although the difference between stock prices of AKBNK-GARAN and ISCTR-YKBNK is getting more, all the prices have a downward trend in 2011

2012

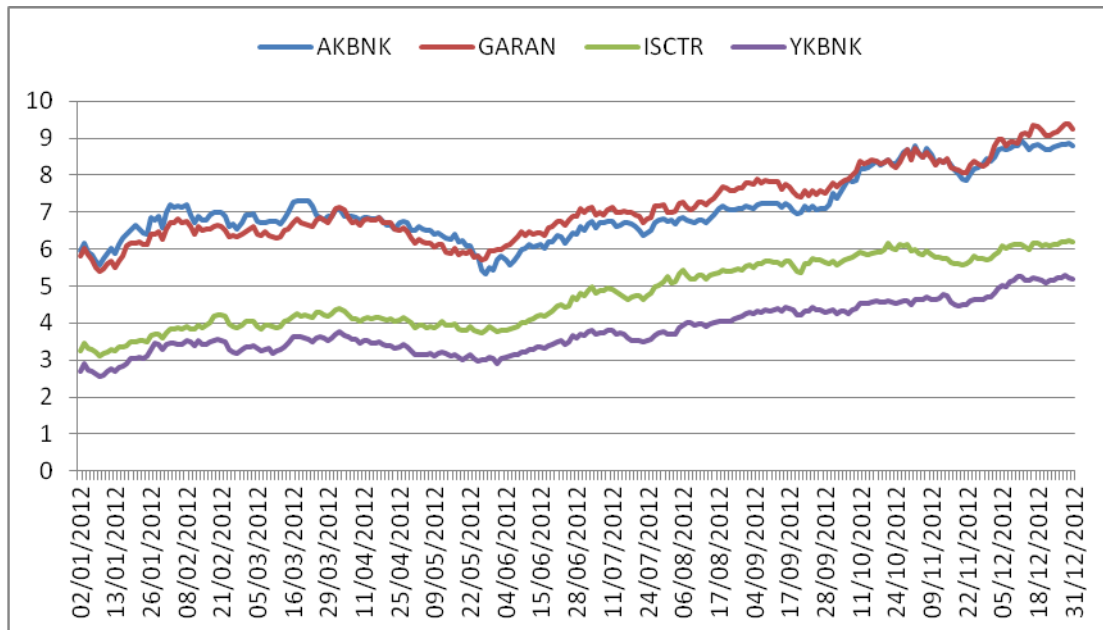


Figure 3.54: 2012 Stock Prices of Four Banks

All the banks have an upward trend and see the top value in this year.

4.3 MODELLING

4.3.1. Model Testing

4.3.1.1. White Noise

A stationary time series ε_t is said to be white noise if

$$\text{Corr}(\varepsilon_t, \varepsilon_s) = 0 \text{ for all } t \neq s$$

Thus ε_t is a sequence of uncorrelated random variables with constant variance and constant mean. This constant mean value is assumed zero. Plots of white noise series exhibit a very erratic, jumpy, unpredictable behavior. Since the ε_t are uncorrelated, previous values do not help us to forecast future values. White noise series themselves are quite uninteresting from a forecasting standpoint (they are not linearly forecastable), but they form the building blocks for more general models. [9]

4.3.1.2. Akaike Information Criteria (AIC)

One of the most commonly used information criteria is AIC. The idea of AIC (Akaike, 1973) is to select the model that minimizes the negative likelihood penalized by the number of parameters as specified in the equation (1).

$$AIC = -2\log p(L) + 2p \quad (1)$$

where L refers to the likelihood under the fitted model and p is the number of parameters in the model.

Specifically, AIC is aimed at finding the best approximating model to the unknown true data generating process and its applications draws from.

4.3.1.3. Bayesian (Schwarz) Information Criteria (BIC)

Another widely used information criteria is the BIC or Schwarz Criteria. Unlike Akaike Information Criteria, BIC is derived within a Bayesian framework as an estimate of the Bayes factor for two competing models (Schwarz, 1978; Kass and Raftery, 1995). BIC is defined as:

$$BIC = -2\log p(L) + p\log(n)$$

Superficially, BIC differs from AIC only in the second term which now depends on sample size n . Models that minimize the Bayesian Information Criteria are selected. From a Bayesian perspective, BIC is designed to find the most probable model given the data.

Performance of the model selection criteria in selecting good models for the observed data is examined using simulation studies. Such a comparison is not straight forward and its relevance could be questioned, given that the two criteria are based on different theoretical motivations and objectives. However, for application purpose, the Akaike Information Criteria and the Bayesian Information Criteria do have the same aim of identifying good models even if they differ in their exact definition of a “good model”. Comparing them is thus justified, at least to examine how each criterion performs according to recovery of the correct model or how they behave when both should prefer the same model. [10]

4.3.2 Application of Model On Data

4.3.2.1. Model of AKBNK



























































Date: 04/17/13 Time: 22:55 Sample: 1 2509 Included observations: 2509					
Autocorrelation	Partial Correlation	AC	PAC	Q-Stat	Prob
		1	0.997	0.997	2497.6 0.000
		2	0.994	-0.008	4981.6 0.000
		3	0.991	0.001	7452.1 0.000
		4	0.988	0.006	9909.3 0.000
		5	0.986	0.020	12354. 0.000
		6	0.983	0.004	14786. 0.000
		7	0.980	0.022	17207. 0.000
		8	0.978	0.014	19616. 0.000
		9	0.976	0.010	22014. 0.000
		10	0.973	0.002	24402. 0.000
		11	0.971	-0.006	26778. 0.000
		12	0.968	-0.004	29144. 0.000
		13	0.966	-0.020	31498. 0.000
		14	0.963	-0.017	33840. 0.000
		15	0.960	0.003	36170. 0.000
		16	0.958	0.005	38488. 0.000
		17	0.955	-0.008	40794. 0.000
		18	0.952	-0.002	43089. 0.000
		19	0.950	-0.004	45372. 0.000
		20	0.947	-0.005	47643. 0.000
		21	0.945	0.055	49903. 0.000
		22	0.943	0.034	52154. 0.000
		23	0.940	-0.026	54396. 0.000
		24	0.938	0.013	56627. 0.000
		25	0.936	0.014	58850. 0.000
		26	0.934	0.005	61063. 0.000
		27	0.932	0.008	63268. 0.000
		28	0.930	0.016	65464. 0.000
		29	0.928	0.008	67652. 0.000

Table 4.1: Correlogram of AKBNK

Equation: AKBNK_EGARCH Workfile: BITIRME::Untitl...				
View	Proc	Object	Print	Name
Dependent Variable: AKBNK_CLOSING Method: ML - ARCH Date: 04/08/13 Time: 20:10 Sample (adjusted): 2 2509 Included observations: 2508 after adjustments Convergence achieved after 23 iterations Presample variance: backcast (parameter = 0.7) LOG(GARCH) = C(2) + C(3)*ABS(RESID(-1)/@SQRT(GARCH(-1))) + C(4)*RESID(-1)/@SQRT(GARCH(-1)) + C(5)*LOG(GARCH(-1))				
Variable	Coefficient	Std. Error	z-Statistic	Prob.
AR(1)	1.001136	0.000473	2116.069	0.0000
Variance Equation				
C(2)	-0.141465	0.012090	-11.70124	0.0000
C(3)	0.147835	0.010604	13.94147	0.0000
C(4)	0.014874	0.007149	2.080640	0.0375
C(5)	0.993495	0.001392	713.6746	0.0000
R-squared	0.996775	Mean dependent var	4.661280	
Adjusted R-squared	0.996775	S.D. dependent var	2.207321	
S.E. of regression	0.125345	Akaike info criterion	-1.690956	
Sum squared resid	39.38848	Schwarz criterion	-1.679339	
Log likelihood	2125.459	Hannan-Quinn criter.	-1.686739	
Durbin-Watson stat	1.982685			
Inverted AR Roots	1.00			
Estimated AR process is nonstationary				

Table 4.2: Equation of EGARCH Model of AKBNK

Firstly Correlogram of AKBNK have to be analyzed. When we look at the correlogram, we see that AR(1) model have to apply on data.

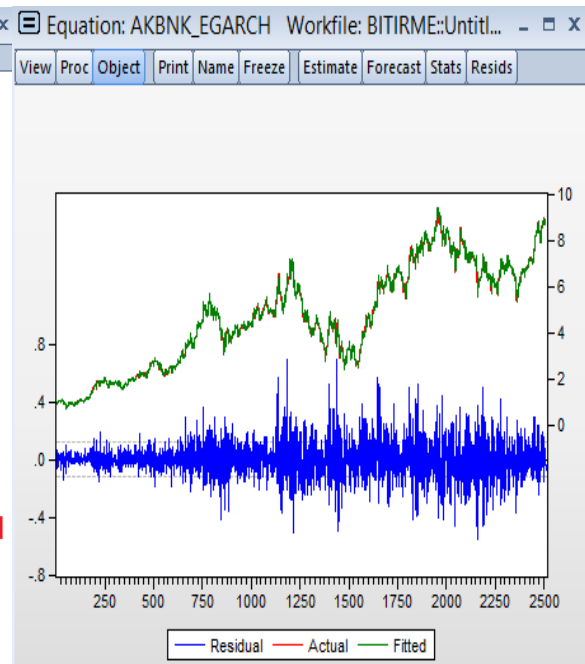


Table 4.3: Actual-Fitted-Residual of EGARCH Model of AKBNK

Correlogram of Standardized Residuals						Correlogram of Standardized Residuals Squared						
Sample: 2 2509 Included observations: 2508 Q-statistic probabilities adjusted for 1 ARMA term(s)						Sample: 2 2509 Included observations: 2508 Q-statistic probabilities adjusted for 1 ARMA term(s)						
Autocorrelation	Partial Correlation	AC	PAC	Q-Stat	Prob	Autocorrelation	Partial Correlation	AC	PAC	Q-Stat	Prob	
		1	0.032	0.032	2.5118			1	0.026	0.026	1.6646	
		2	0.010	0.009	2.7454	0.098		2	0.069	0.068	13.538	0.000
		3	-0.007	-0.007	2.8611	0.239		3	-0.004	-0.007	13.578	0.001
		4	-0.026	-0.025	4.5087	0.212		4	0.036	0.032	16.829	0.001
		5	-0.011	-0.009	4.8118	0.307		5	0.010	0.009	17.085	0.002
		6	-0.030	-0.029	7.1374	0.211		6	-0.018	-0.023	17.910	0.003
		7	-0.000	0.002	7.1374	0.308		7	-0.006	-0.006	17.995	0.006
		8	-0.030	-0.030	9.4036	0.225		8	-0.006	-0.004	18.098	0.012
		9	-0.011	-0.010	9.7043	0.286		9	-0.025	-0.025	19.626	0.012
		10	0.047	0.046	15.191	0.086		10	0.014	0.018	20.153	0.017
		11	0.018	0.014	16.005	0.099		11	-0.006	-0.003	20.255	0.027
		12	0.024	0.020	17.482	0.094		12	0.027	0.025	22.117	0.023
		13	0.010	0.008	17.746	0.124		13	-0.007	-0.006	22.253	0.035
		14	-0.006	-0.007	17.840	0.164		14	0.027	0.023	24.106	0.030
		15	-0.011	-0.009	18.135	0.201		15	-0.033	-0.034	26.837	0.020
		16	0.013	0.017	18.576	0.234		16	-0.038	-0.041	30.470	0.010
		17	0.002	0.002	18.590	0.290		17	-0.001	0.006	30.472	0.016
		18	0.009	0.013	18.816	0.339		18	-0.037	-0.034	33.949	0.009
		19	-0.000	0.001	18.816	0.403		19	0.001	0.005	33.952	0.013
		20	-0.065	-0.066	29.394	0.060		20	0.005	0.015	34.028	0.018
		21	-0.035	-0.032	32.517	0.038		21	-0.041	-0.042	38.274	0.008
		22	0.021	0.023	33.619	0.040		22	-0.021	-0.021	39.431	0.009
		23	-0.010	-0.014	33.895	0.050		23	-0.017	-0.009	40.207	0.010
		24	0.006	0.004	34.001	0.065		24	0.002	-0.001	40.222	0.015
		25	0.007	0.006	34.129	0.082		25	-0.015	-0.011	40.768	0.018
		26	0.040	0.036	38.107	0.045		26	0.036	0.039	44.077	0.011
		27	-0.009	-0.013	38.295	0.057		27	-0.027	-0.028	45.911	0.009
		28	-0.015	-0.020	38.900	0.065		28	0.011	0.008	46.200	0.012
		29	0.003	0.000	38.928	0.082		29	-0.013	-0.008	46.635	0.015
		30	-0.038	-0.029	42.531	0.050		30	0.016	0.013	47.284	0.017
		31	-0.026	-0.019	44.260	0.045		31	0.005	0.004	47.360	0.023
		32	0.013	0.018	44.698	0.053		32	0.014	0.013	47.873	0.027
		33	-0.022	-0.020	45.910	0.053		33	0.007	0.006	48.006	0.034
		34	-0.026	-0.028	47.669	0.047		34	-0.014	-0.020	48.512	0.040
		35	0.013	0.012	48.122	0.055		35	0.001	0.007	48.515	0.051
		36	-0.012	-0.018	48.482	0.064		36	-0.008	-0.011	48.685	0.062

Table 4.4: Residual Cor. of EGARCH Model of AKBNK Table 4.5: Residual Squared Cor. of EGARCH Model of AKBNK

When we apply AR model with EGARCH method, R- Squared is nearly 1. Our Actual and Fitted graphs are acting like each other also our correlogram of q-statics and correlogram of squared residuals have no lag.

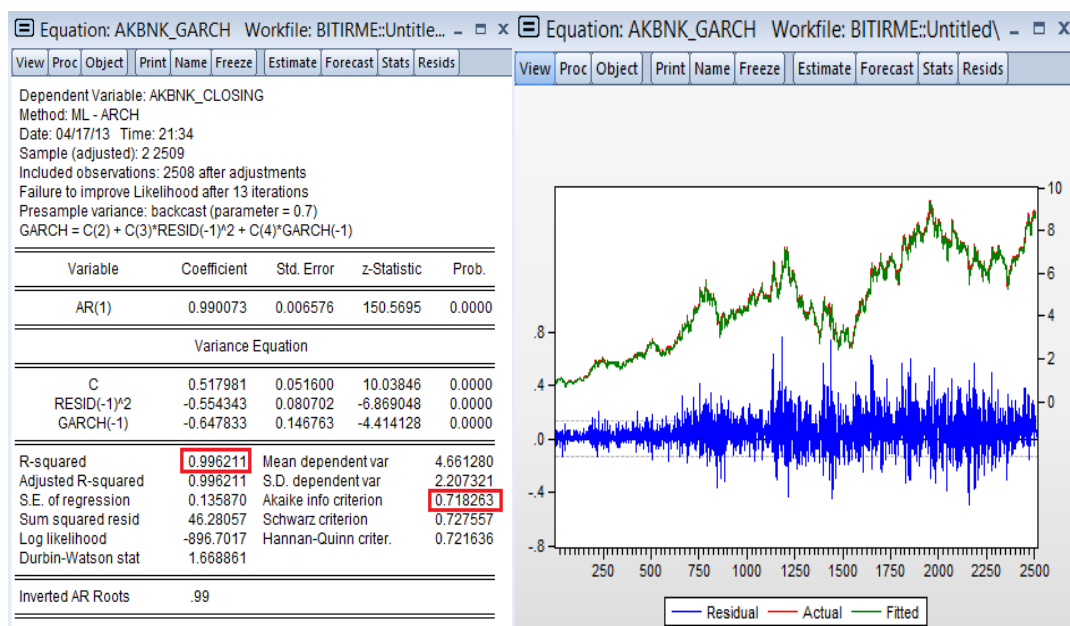


Table 4.6: Equation of GARCH Model of AKBNK

Table 4.7: Actual-Fitted-Residual of GARCH Model of AKBNK

Correlogram of Standardized Residuals							Correlogram of Standardized Residuals Squared						
Date: 04/17/13 Time: 22:50 Sample: 2 2509 Included observations: 2508 Q-statistic probabilities adjusted for 1 ARMA term(s)							Date: 04/17/13 Time: 22:53 Sample: 2 2509 Included observations: 2508 Q-statistic probabilities adjusted for 1 ARMA term(s)						
Autocorrelation	Partial Correlation	AC	PAC	Q-Stat	Prob		Autocorrelation	Partial Correlation	AC	PAC	Q-Stat	Prob	
		1	0.052	0.052	6.8130				1	0.174	0.174	76.239	
		2	0.024	0.021	8.2468	0.004			2	0.135	0.108	122.24	0.000
		3	0.007	0.005	8.3702	0.015			3	0.139	0.104	170.85	0.000
		4	0.005	0.004	8.4311	0.038			4	0.117	0.070	205.28	0.000
		5	0.025	0.024	10.018	0.040			5	0.178	0.132	284.74	0.000
		6	-0.006	-0.008	10.098	0.073			6	0.085	0.014	303.10	0.000
		7	-0.009	-0.010	10.316	0.112			7	0.118	0.062	338.16	0.000
		8	0.001	0.002	10.319	0.171			8	0.102	0.037	364.55	0.000
		9	0.021	0.021	11.440	0.178			9	0.107	0.047	393.40	0.000
		10	0.048	0.046	17.303	0.044			10	0.094	0.023	415.67	0.000
		11	0.038	0.033	20.879	0.022			11	0.093	0.036	437.57	0.000
		12	0.046	0.041	26.149	0.006			12	0.098	0.033	462.03	0.000
		13	0.055	0.049	33.785	0.001			13	0.083	0.020	479.30	0.000
		14	0.038	0.030	37.500	0.000			14	0.112	0.051	511.23	0.000
		15	0.015	0.007	38.059	0.001			15	0.071	0.003	523.84	0.000
		16	0.040	0.037	42.113	0.000			16	0.063	-0.000	533.86	0.000
		17	0.037	0.033	45.626	0.000			17	0.123	0.068	571.99	0.000
		18	0.029	0.023	47.701	0.000			18	0.066	-0.002	583.14	0.000
		19	0.035	0.030	50.813	0.000			19	0.074	0.010	597.11	0.000
		20	-0.045	-0.052	56.023	0.000			20	0.087	0.031	616.18	0.000
		21	-0.019	-0.021	56.912	0.000			21	0.074	0.013	629.88	0.000
		22	0.065	0.062	67.727	0.000			22	0.061	-0.008	639.34	0.000
		23	0.014	0.001	68.254	0.000			23	0.075	0.025	653.41	0.000
		24	0.014	0.003	68.753	0.000			24	0.070	0.011	665.93	0.000
		25	0.032	0.027	71.402	0.000			25	0.088	0.032	685.60	0.000
		26	0.034	0.022	74.397	0.000			26	0.097	0.038	709.31	0.000
		27	0.020	0.002	75.428	0.000			27	0.082	0.022	726.21	0.000
		28	0.013	0.000	75.832	0.000			28	0.095	0.030	748.92	0.000
		29	0.023	0.014	77.217	0.000			29	0.064	-0.002	759.23	0.000
		30	0.009	0.001	77.403	0.000			30	0.093	0.033	780.99	0.000
		31	0.014	0.008	77.886	0.000			31	0.096	0.026	804.26	0.000
		32	0.059	0.052	86.673	0.000			32	0.080	0.015	820.44	0.000
		33	-0.015	-0.023	87.208	0.000			33	0.052	-0.018	827.31	0.000
		34	-0.020	-0.026	88.189	0.000			34	0.076	0.016	842.09	0.000
		35	0.027	0.018	90.018	0.000			35	0.134	0.075	887.63	0.000
		36	0.023	0.014	91.330	0.000			36	0.089	0.016	907.59	0.000

Table 4.8: Residual Cor. Of GARCH Model of AKBNK

Table 4.9: Residual Squared Cor. Of GARCH Model of AKBNK

When we apply AR model with GARCH method, R- Squared is nearly 1 but smaller than EGARCH R-Squared. On the other hand GARCH method's absolute Akaike Criterion is smaller than EGARCH method. This means that we should use GARCH Method. Actual and Fitted graphs are also acting like each other and our correlogram of q-statics has no lag. But our correlogram of squared residuals has lags This means that GARCH method is not suitable for our data. We must use EGARCH method for AKBNK and the other banks (GARAN, ISCTR, YKBNK).

4.3.2.2. Model of GARAN

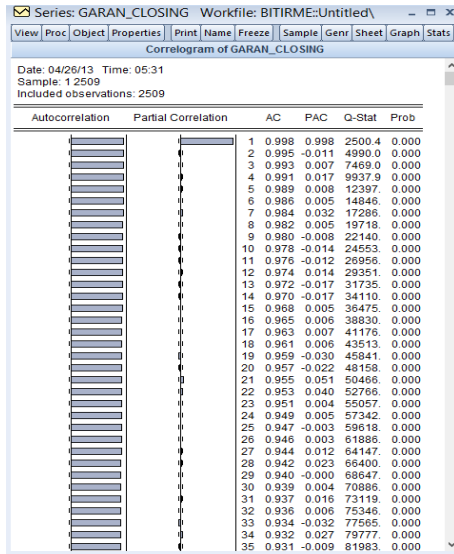


Table 4.10: Correlogram of GARAN

Equation: GARAN_EGARCH Workfile: BITIRME::Untitl...

View Proc Object Print Name Freeze Estimate Forecast Stats Resids

Dependent Variable: GARAN_CLOSING
Method: ML - ARCH
Date: 04/08/13 Time: 20:19
Sample (adjusted): 2 2509
Included observations: 2508 after adjustments
Convergence achieved after 21 iterations
Presample variance: backcast (parameter = 0.7)
LOG(GARCH) = C(2) + C(3)*ABS(RESID(-1))/SQRT(GARCH(-1)) + C(4)*RESID(-1)/SQRT(GARCH(-1)) + C(5)*LOG(GARCH(-1))

Variable	Coefficient	Std. Error	z-Statistic	Prob.
AR(1)	1.001654	0.000469	2136.919	0.0000

Variance Equation

	Coefficient	Std. Error	z-Statistic	Prob.
C(2)	-0.071086	0.008760	-8.114442	0.0000
C(3)	0.082280	0.008732	9.423145	0.0000
C(4)	0.040973	0.005804	7.059070	0.0000
C(5)	0.998124	0.000582	1716.240	0.0000

R-squared 0.998038 Mean dependent var 3.874091
Adjusted R-squared 0.998038 S.D. dependent var 2.467931
S.E. of regression 0.109302 Akaike info criterion -2.279317
Sum squared resid 29.95083 Schwarz criterion -2.267700
Log likelihood 2863.264 Hannan-Quinn criter. -2.275100
Durbin-Watson stat 2.004158

Inverted AR Roots 1.00
Estimated AR process is nonstationary

Table 4.11: Equation of EGARCH Model of GARAN

Firstly Correlogram of GARAN have to be analyzed. When we look at the correlogram, we see that AR(1) model have to apply on data.

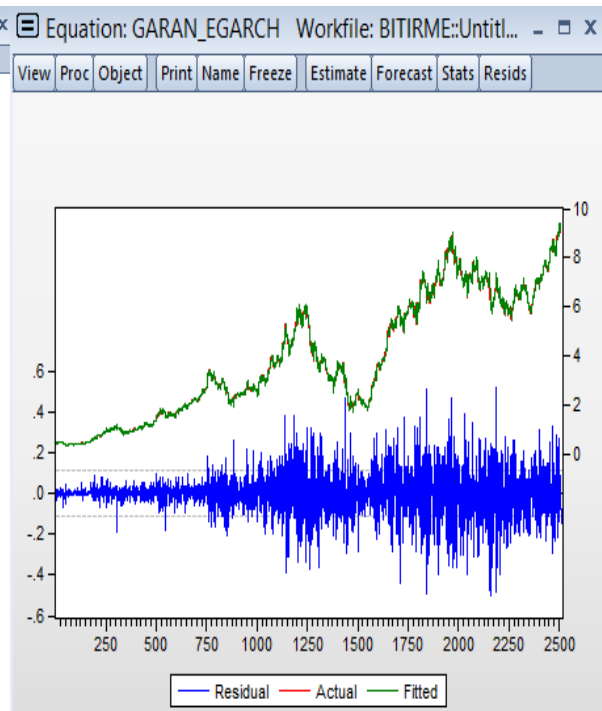


Table 4.12: Actual-Fitted-Residual of EGARCH Model of GARAN

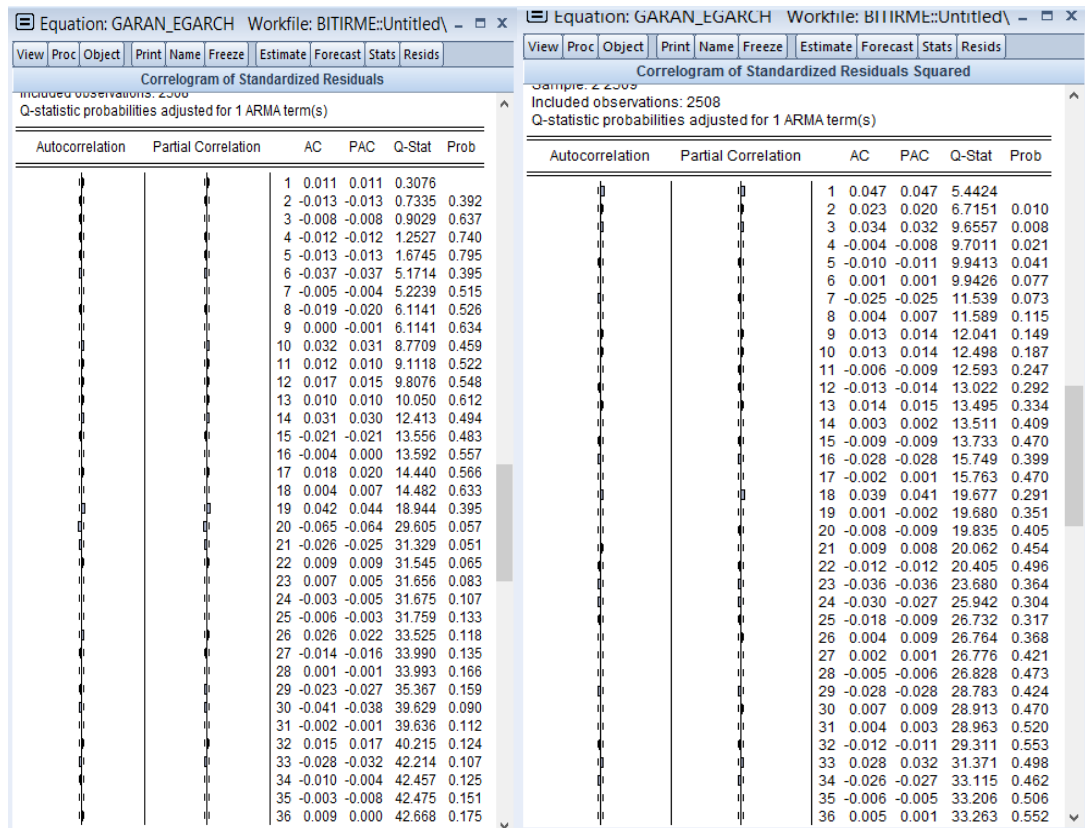


Table 4.13: Residual Cor. Of GARCH Model of AKBNK

Table 4.14: Residual Squared Cor. Of GARCH Model of AKBNK

When we apply AR model with EGARCH method, R- Squared is nearly 1. Our Actual and Fitted graphs are acting like each other also our correlogram of q-statics and correlogram of squared residuals have no lag.

4.3.2.3. Model of ISCTR

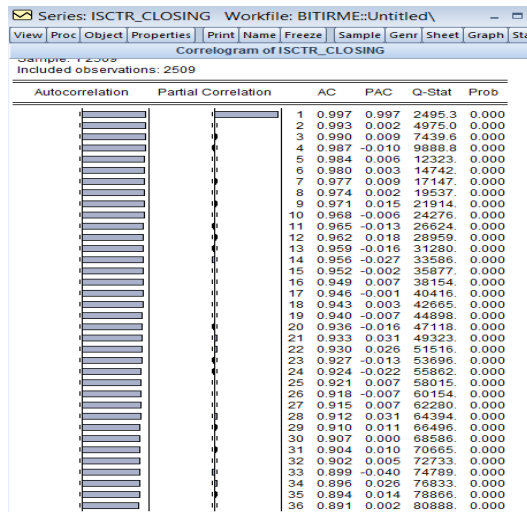


Table 4.15: Correlogram of ISCTR

Firstly Correlogram of ISCTR have to be analyzed. When we look at the correlogram, we see that AR(1) model have to apply on data.

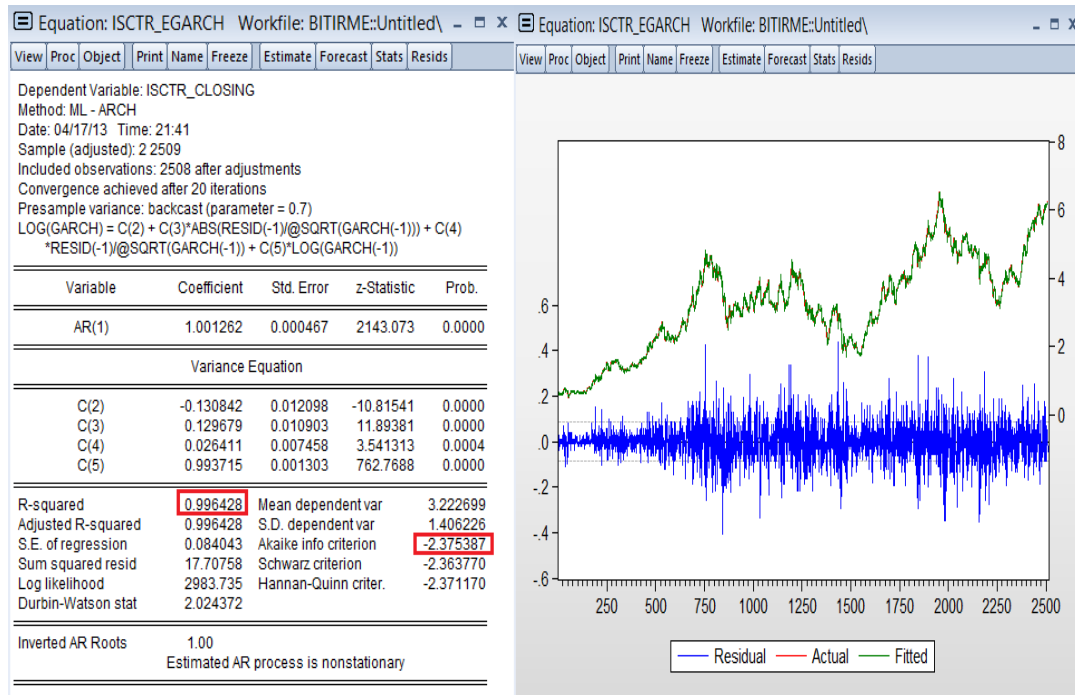


Table 4.16: Equation of EGARCH Model of ISCTR

Table 4.17: Actual-Fitted-Residual of EGARCH Model of ISCTR

Equation: ISCTR_EGARCH Workfile: BITIRME::Untitled\ - x										Equation: ISCTR_EGARCH Workfile: BITIRME::Untitled\ - x									
View	Proc	Object	Print	Name	Freeze	Estimate	Forecast	Stats	Resids	View	Proc	Object	Print	Name	Freeze	Estimate	Forecast	Stats	Resids
Correlogram of Standardized Residuals										Correlogram of Standardized Residuals Squared									
Included observations: 2500										Included observations: 2500									
Q-statistic probabilities adjusted for 1 ARMA term(s)										Q-statistic probabilities adjusted for 1 ARMA term(s)									
Autocorrelation		Partial Correlation		AC	PAC	Q-Stat	Prob	Autocorrelation		Partial Correlation		AC	PAC	Q-Stat	Prob				
				1	0.006	0.006	0.0828					1	0.020	0.020	0.9558				
				2	-0.010	-0.010	0.3198	0.572				2	0.048	0.047	6.6534	0.010			
				3	0.007	0.007	0.4390	0.803				3	-0.003	-0.004	6.6696	0.036			
				4	-0.015	-0.015	1.0155	0.797				4	0.021	0.019	7.8222	0.050			
				5	0.013	0.014	1.4701	0.832				5	0.018	0.018	8.6499	0.070			
				6	-0.019	-0.019	2.3574	0.798				6	-0.004	-0.007	8.6901	0.122			
				7	0.000	0.001	2.3574	0.884				7	-0.013	-0.014	9.1057	0.168			
				8	-0.027	-0.027	4.1357	0.764				8	-0.029	-0.028	11.186	0.131			
				9	0.010	0.011	4.3682	0.822				9	0.003	0.004	11.204	0.190			
				10	0.042	0.041	8.8629	0.450				10	-0.010	-0.008	11.468	0.245			
				11	-0.014	-0.014	9.3657	0.498				11	-0.002	-0.001	11.476	0.322			
				12	0.017	0.016	10.058	0.525				12	0.013	0.015	11.882	0.373			
				13	0.025	0.025	11.619	0.477				13	0.010	0.010	12.123	0.436			
				14	-0.009	-0.009	11.820	0.542				14	-0.011	-0.013	12.412	0.494			
				15	-0.020	-0.021	12.800	0.542				15	-0.040	-0.041	16.414	0.289			
				16	-0.007	-0.006	12.932	0.608				16	-0.033	-0.032	19.115	0.209			
				17	0.011	0.012	13.264	0.653				17	-0.014	-0.011	19.630	0.237			
				18	-0.000	0.002	13.264	0.718				18	-0.043	-0.040	24.274	0.112			
				19	0.041	0.041	17.548	0.486				19	0.013	0.018	24.672	0.134			
				20	-0.027	-0.029	19.407	0.431				20	-0.002	0.005	24.683	0.171			
				21	-0.019	-0.016	20.325	0.438				21	0.001	0.001	24.688	0.214			
				22	0.008	0.004	20.485	0.491				22	-0.022	-0.022	25.928	0.209			
				23	0.012	0.011	20.852	0.530				23	-0.027	-0.029	27.768	0.183			
				24	-0.006	-0.007	20.955	0.584				24	0.016	0.016	28.439	0.200			
				25	-0.004	-0.001	20.996	0.639				25	-0.007	-0.008	28.568	0.237			
				26	0.018	0.017	21.801	0.647				26	0.004	0.001	28.618	0.280			
				27	-0.043	-0.042	26.483	0.437				27	0.013	0.019	29.067	0.308			
				28	-0.003	-0.003	26.503	0.491				28	-0.020	-0.020	30.104	0.309			
				29	0.004	-0.001	26.536	0.544				29	0.030	0.029	32.383	0.259			
				30	-0.019	-0.016	27.464	0.547				30	-0.020	-0.022	33.381	0.263			
				31	-0.006	-0.007	27.545	0.595				31	0.008	0.002	33.537	0.300			
				32	0.025	0.025	29.188	0.559				32	-0.014	-0.015	34.039	0.323			
				33	-0.034	-0.034	32.179	0.458				33	0.009	0.003	34.235	0.361			
				34	-0.030	-0.026	34.429	0.399				34	0.018	0.019	35.043	0.371			
				35	0.006	0.002	34.519	0.443				35	0.004	0.005	35.092	0.416			
				36	-0.036	-0.040	37.839	0.341				36	0.002	-0.002	35.098	0.464			

Table 4.18: Residual Cor. Of GARCH Model of ISCTR Table 4.19: Residual Squared Cor. Of GARCH Model of ISCTR

When we apply AR model with EGARCH method, R- Squared is nearly 1. Our Actual and Fitted graphs are acting like each other also our correlogram of q-statics and correlogram of squared residuals have no lag.

4.3.2.4. Model of YKBNK

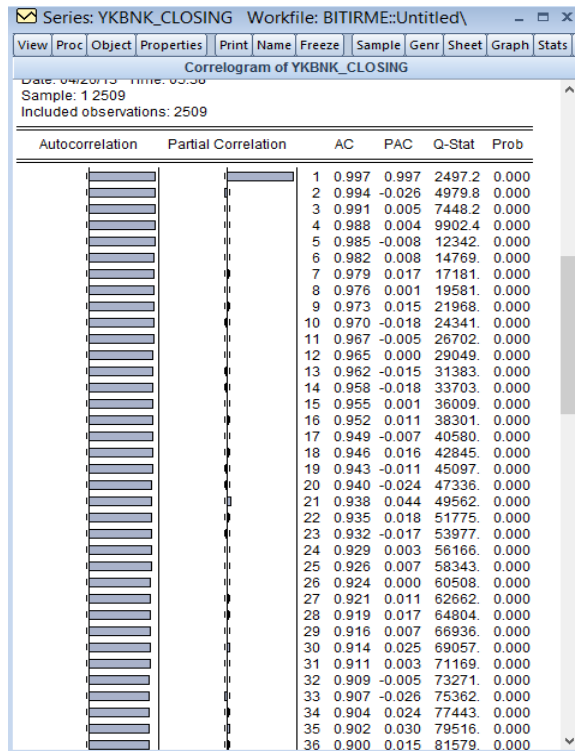


Table 4.20: Correlogram of YKBNK

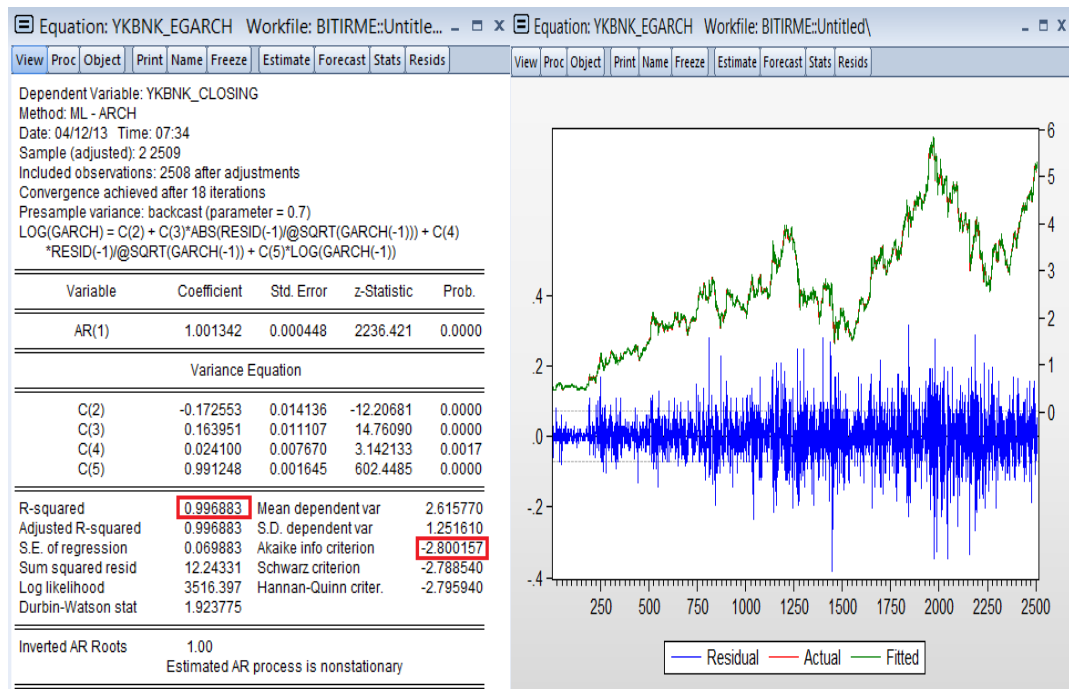


Table 4.21: Equation of EGARCH Model of YKBNK

Table 4.22: Actual-Fitted-Residual of EGARCH Model of YKBNK

Equation: YKBNK_EGARCH Workfile: BITIRME::Untitled\

ViewProcObjectPrintNameFreezeEstimateForecastStatsResids

Correlogram of Standardized Residuals

Sample: 2 2508
Included observations: 2508
Q-statistic probabilities adjusted for 1 ARMA term(s)

AutocorrelationPartial CorrelationACPACQ-StatProb

Table 4.23: Residual Cor. Of GARCH Model of YKBNK Table 4.24: Residual Squared Cor. Of GARCH Model of YKBNK

When we apply AR model with EGARCH method, R- Squared is nearly 1. Our Actual and Fitted graphs are acting like each other also our correlogram of q-statics and correlogram of squared residuals have no lag.

4.4 FORECAST

4.4.1 Mean Square Error

The mean square error (MSE) of an estimator $\hat{\theta}$ of a parameter θ is the function of θ defined by $E(\hat{\theta} - \theta)^2$ and this is denoted as $MSE_{\hat{\theta}}$.

The MSE measures the average squared difference between the estimator $\hat{\theta}$ and the parameter θ , o somewhat reasonable measure of performance of an estimator.

$$MSE_{\hat{\theta}} = E(\hat{\theta} - \theta)^2 = Var(\hat{\theta}) \quad [11]$$

4.4.2. Forecast of AKBNK

Our data will be forecasted step by step in 4 degree. We mentioned that there are two types of forecast. Static forecast and Dynamic Forecast. We use static forecast at the first step. Dynamic forecast is used for the other steps.

4.4.2.1. First Step

At the first step, we forecast last 5 terms in our data which are modelled by AR with EGARCH and our forecast method is static forecast.

Table 4.25: Forecast of AKBNK at first step

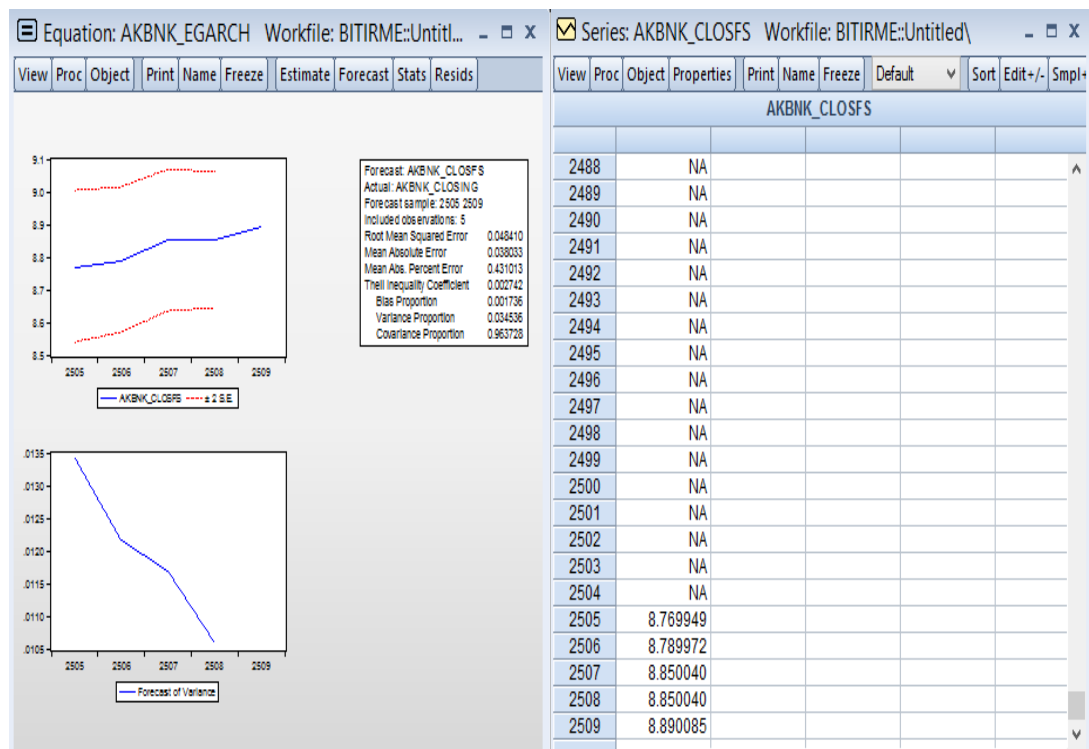


Table 4.26: Forecast Graph of Step 1

Table 4.27: Forecast Values of Step 1

4.4.2.2 Second Step

Forecast

Forecast of: Equation: AKBNK_F1_EGARCH Series: AKBNK_F1

Series names

Forecast name: akbnk_f1f
S.E. (optional):
GARCH(optional):

Method

☒ Dynamic forecast
☐ Static forecast
☐ Structural (ignore ARMA)
☒ Coef uncertainty in S.E. calc

Forecast sample

2510 2514

Output

☒ Forecast graph
☒ Forecast evaluation

☐ Insert actuals for out-of-sample observations

OK Cancel

At the second step, we forecast last 5 terms again after first 5 forecasted terms added end of the first model and modelled again by AR with EGARCH. Our forecast method is dynamic forecast.

Table 4.71: Forecast of AKBNK at second step

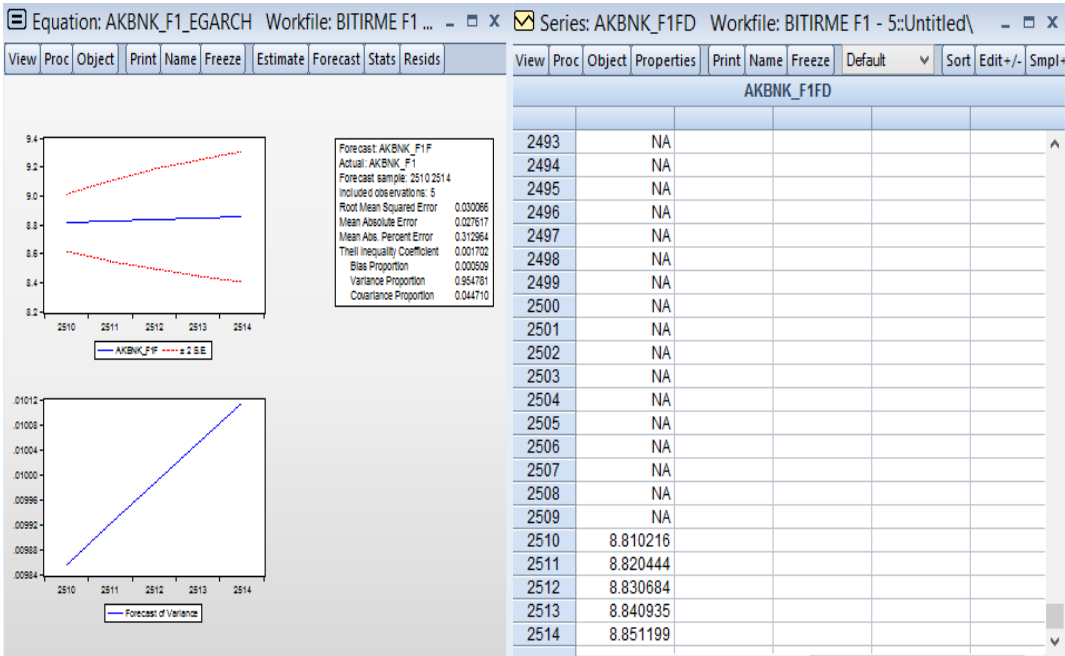


Table 4.28: Forecast Graph of Step 2

Table 4.29: Forecast Values of Step 2

4.4.2.3. Third Step

Forecast

Forecast of
Equation: AKBNK_F2_EGARCH Series: AKBNK_F2

Series names
Forecast name: akbnk_f2f
S.E. (optional):
GARCH(optional):

Method
☒ Dynamic forecast
☐ Static forecast
☐ Structural (ignore ARMA)
☒ Coef uncertainty in S.E. calc

Forecast sample
2515 2519

Output
☒ Forecast graph
☒ Forecast evaluation

☐ Insert actuals for out-of-sample observations

OK Cancel

At the Third step, we forecast last 5 terms again after first 5 forecasted terms added end of the first model and modelled again by AR with EGARCH. Our forecast method is dynamic forecast.

Table 4.30: Forecast of AKBNK at third step

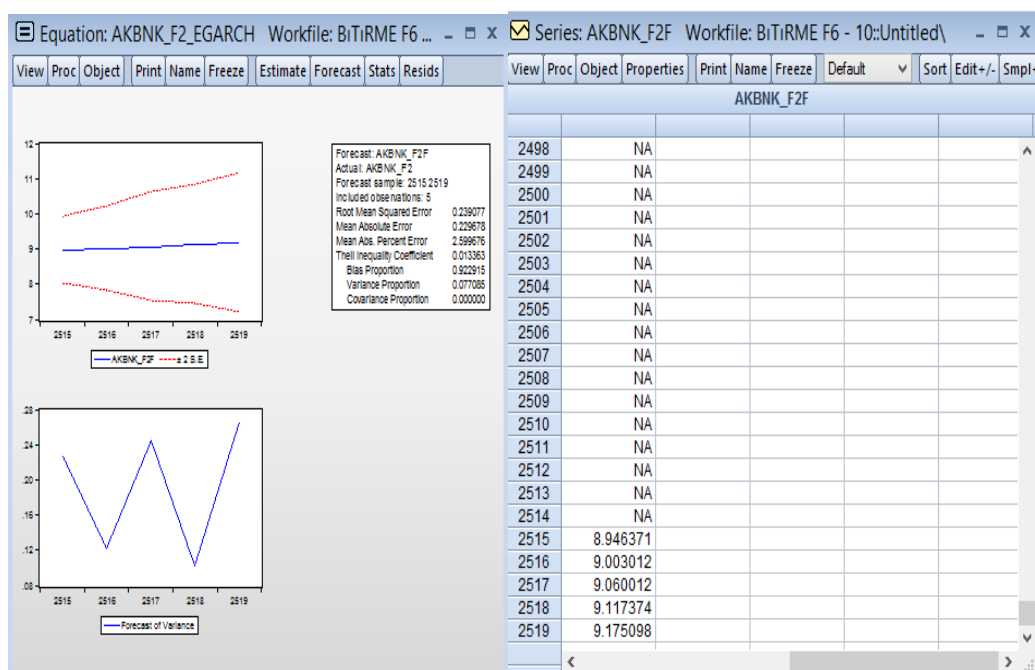


Table 4.31: Forecast Graph of Step 3

Table 4.32: Forecast Values of Step 3

4.4.2.4 Fourth Step

Forecast

Forecast of: Series: AKBNK_F3

Series names

Forecast name:

S.E. (optional):

GARCH(optional):

Method

☒ Dynamic forecast

☐ Static forecast

☐ Structural (ignore ARMA)

☒ Coef uncertainty in S.E. calc

Forecast sample

Output

☒ Forecast graph

☒ Forecast evaluation

☐ Insert actuals for out-of-sample observations

At the Fourth step, we forecast last 5 terms again after first 5 forecasted terms added end of the first model and modelled again by AR with EGARCH. Our forecast method is dynamic forecast.

Table 4.33: Forecast of AKBNK at fourth step

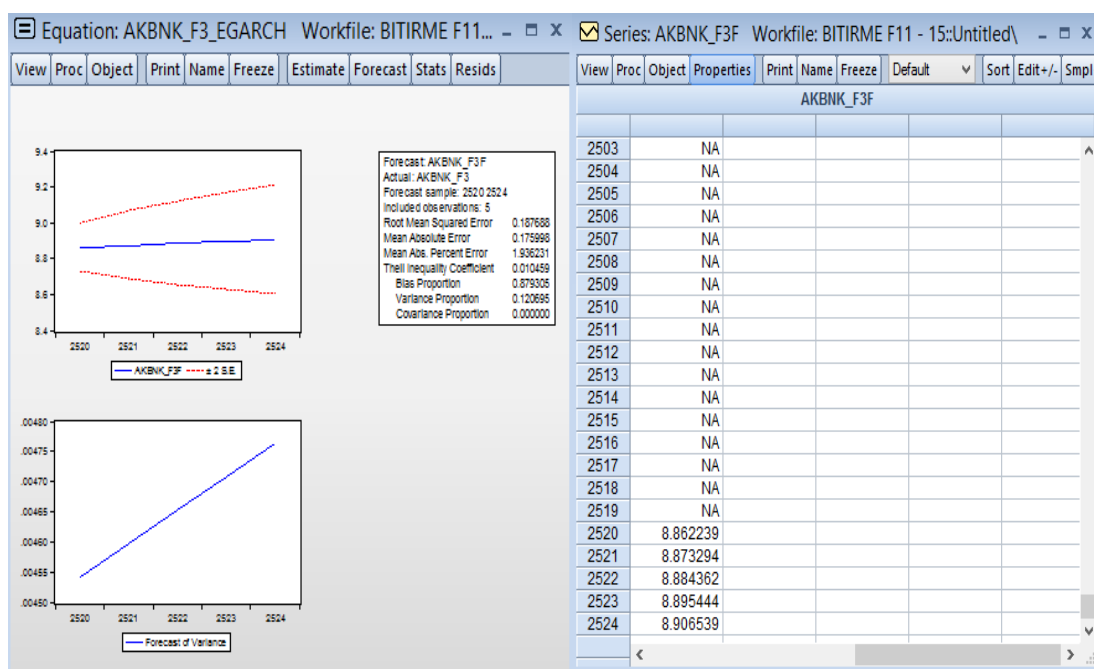


Table 4.34: Forecast Graph of Step 4

Table 4.35: Forecast Values of Step 4

Date	Real Values	Forecasted Values	RV-FV	difference %
02/01/2013	8,96	8,769	0,191	2,178127495
03/01/2013	9,04	8,789	0,251	2,85584253
04/01/2013	8,98	8,85	0,13	1,468926554
07/01/2013	9,02	8,85	0,17	1,920903955
08/01/2013	9,04	8,89	0,15	1,687289089
09/01/2013	9,02	8,81	0,21	2,383654938
10/01/2013	9,08	8,82	0,26	2,947845805
11/01/2013	9	8,83	0,17	1,925254813
14/01/2013	9,16	8,84	0,32	3,619909502
15/01/2013	9,2	8,85	0,35	3,95480226
16/01/2013	9,48	8,95	0,53	5,921787709
17/01/2013	9,8	9	0,8	8,888888889
18/01/2013	9,86	9,06	0,8	8,830022075
21/01/2013	9,88	9,12	0,76	8,333333333
22/01/2013	10	9,18	0,82	8,932461874
23/01/2013	10,08	8,86	1,22	13,76975169
24/01/2013	10,25	8,87	1,38	15,55806088
25/01/2013	9,86	8,88	0,98	11,03603604
28/01/2013	9,3	8,9	0,4	4,494382022
29/01/2013	9,42	8,91	0,51	5,723905724

5,821559359 Average Difference

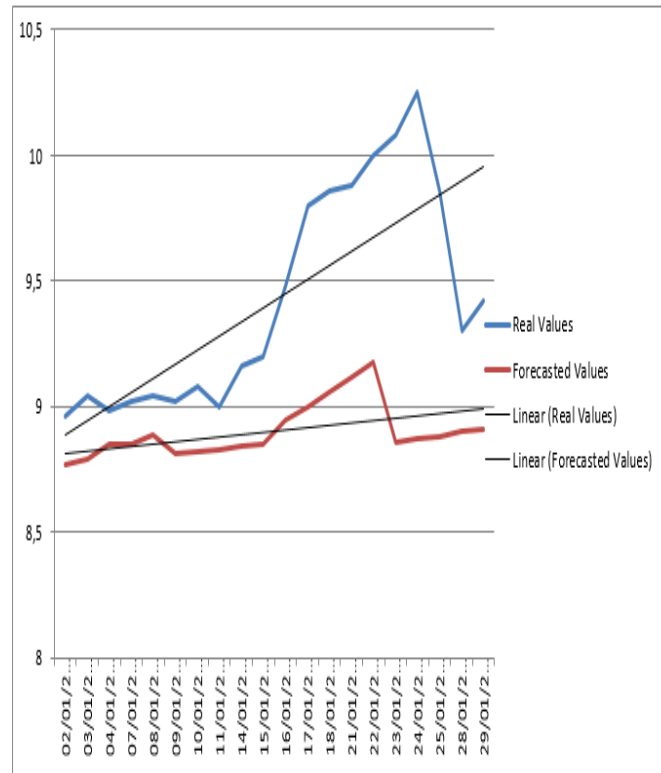


Figure 4.1: Comparison of Real Values and Forecasted Values of AKBNK

Forecast result of AKBNK is successful, because real values and forecasted values are acting like each other. The biggest difference is graph of real values shifted up. This is the result of political choices.

4.4.3 Forecast of GARAN

Our data will be forecasted step by step in 4 degree. We mentioned that there are two types of forecast. Static forecast and Dynamic Forecast. We use static forecast at the first step. Dynamic forecast is used for the other steps.

4.4.3.1 First Step

At the first step, we forecast last 5 terms in our data which are modelled by AR with EGARCH and our forecast method is static forecast.

Table 4.36: Forecast of GARAN at first step

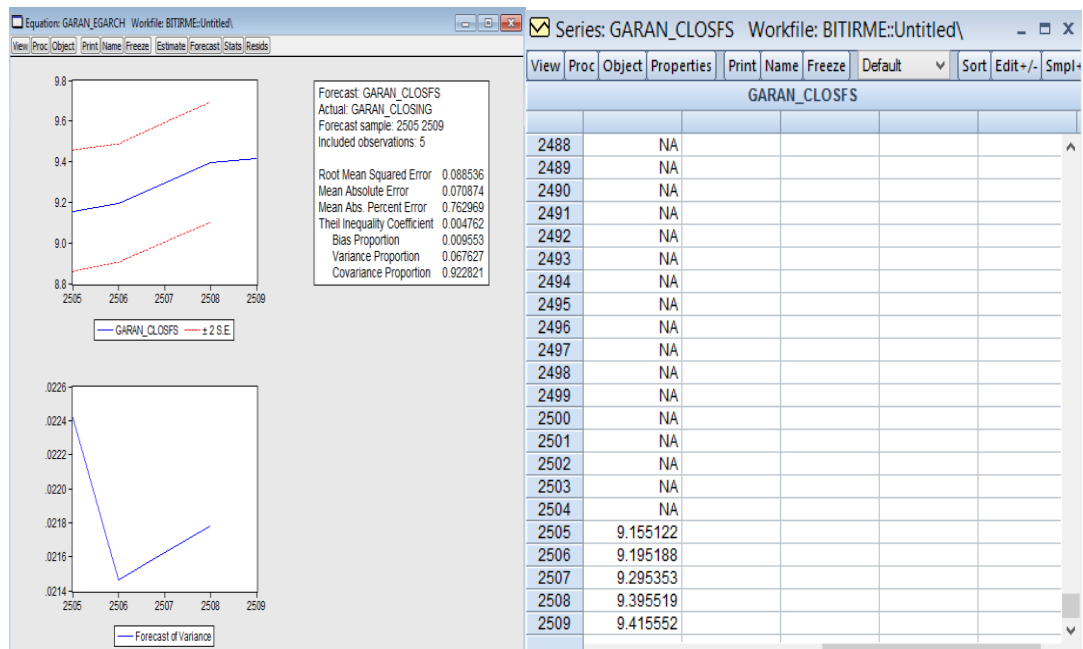


Table 4.37: Forecast Graph of Step 1

Table 4.38: Forecast Values of Step 1

4.4.3.2 Second Step

Forecast

Forecast of
Equation: GARAN_F1_EGARCH Series: GARAN_F1

Series names
Forecast name: garan_f1fd
S.E. (optional):
GARCH(optional):

Method
☒ Dynamic forecast
☐ Static forecast
☐ Structural (ignore ARMA)
☒ Coef uncertainty in S.E. calc

Forecast sample
2510 2514

Output
☒ Forecast graph
☒ Forecast evaluation

☐ Insert actuals for out-of-sample observations

OK Cancel

At the second step, we forecast last 5 terms again after first 5 forecasted terms added end of the first model and modelled again by AR with EGARCH. Our forecast method is dynamic forecast.

Table 4.39: Forecast of GARAN at second step

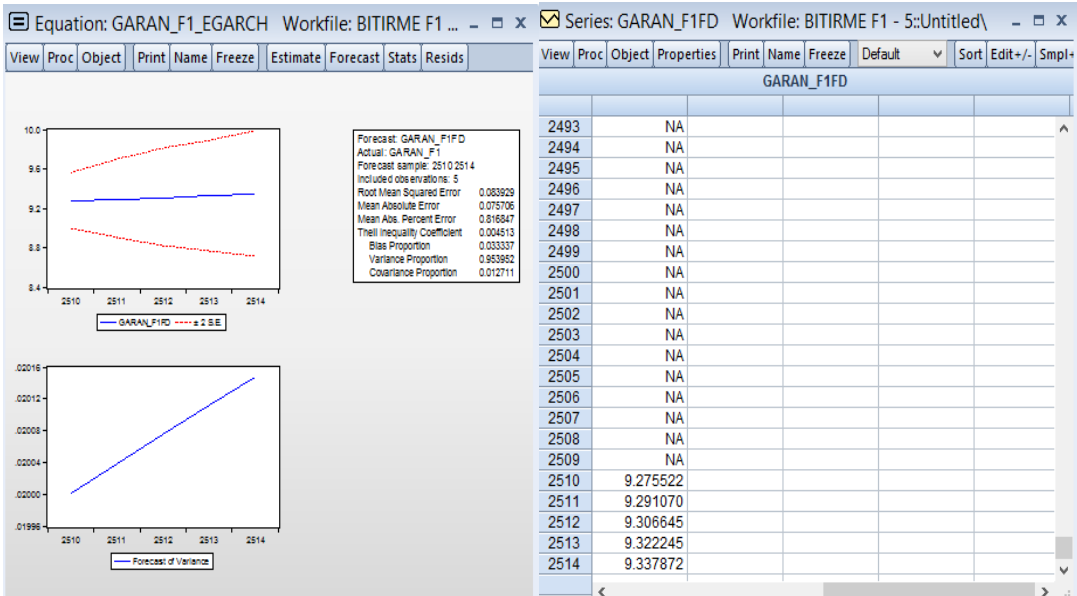


Table 4.40: Forecast Graph of Step 2

Table 4.41: Forecast Values of Step 2

4.4.3.3 Third Step

Forecast

Forecast of: Series: GARAN_F2

Series names

Forecast name:

S.E. (optional):

GARCH(optional):

Method

☒ Dynamic forecast

☐ Static forecast

☐ Structural (ignore ARMA)

☒ Coef uncertainty in S.E. calc

Forecast sample

Output

☒ Forecast graph

☒ Forecast evaluation

☐ Insert actuals for out-of-sample observations

OK Cancel

At the Third step, we forecast last 5 terms again after first 5 forecasted terms added end of the first model and modelled again by AR with EGARCH. Our forecast method is dynamic forecast.

Table 4.42: Forecast of GARAN at third step

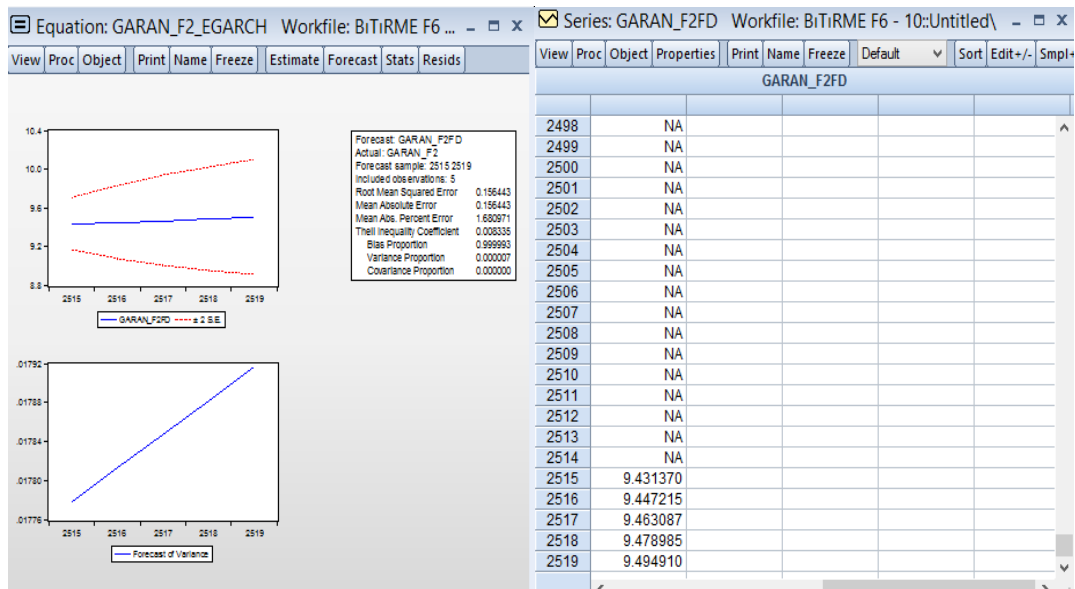


Table 4.43: Forecast Graph of Step 3

Table 4.44: Forecast Values of Step 3

4.4.3.4 Fourth Step

Forecast

Forecast of: Series: GARAN_F3

Series names

Forecast name:

S.E. (optional):

GARCH(optional):

Method

☒ Dynamic forecast

☐ Static forecast

☐ Structural (ignore ARMA)

☒ Coef uncertainty in S.E. calc

Forecast sample

Output

☒ Forecast graph

☒ Forecast evaluation

☐ Insert actuals for out-of-sample observations

At the Fourth step, we forecast last 5 terms again after first 5 forecasted terms added end of the first model and modelled again by AR with EGARCH. Our forecast method is dynamic forecast.

Table 4.45: Forecast of GARAN at fourth step

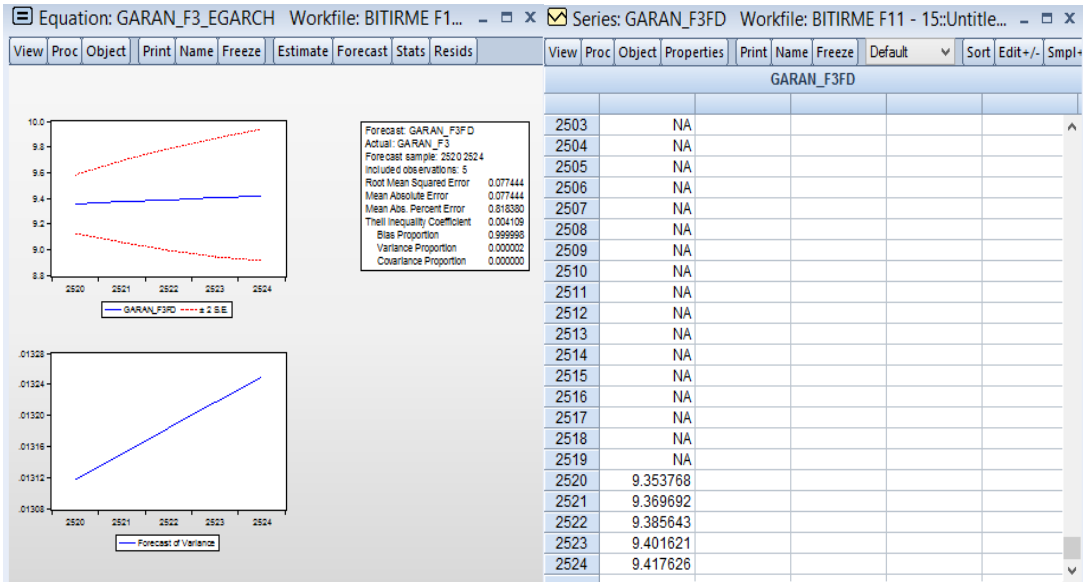


Table 4.46: Forecast Graph of Step 4

Table 4.47: Forecast Values of Step 4

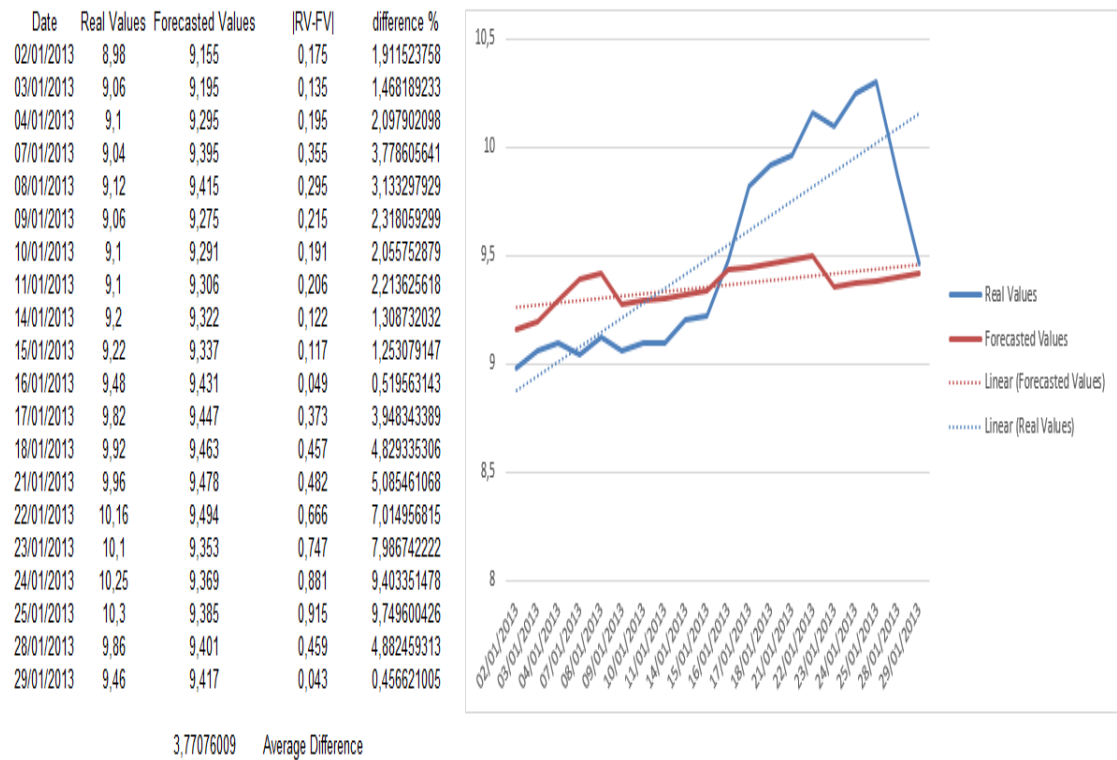


Figure 4.2: Comparison of Real Values and Forecasted Values of GARAN

Forecast result of GARAN is successful, because last data of real values and last data of forecasted values are very close. This means that when we make a long term investment we can benefit from this study.

4.4.4. Forecast of ISCTR

Our data will be forecasted step by step in 4 degree. We mentioned that there are two types of forecast. Static forecast and Dynamic Forecast. We use static forecast at the first step. Dynamic forecast is used for the other steps.

4.4.4.1 First Step

At the first step, we forecast last 5 terms in our data which are modelled by AR with EGARCH and our forecast method is static forecast.

Table 4.48: Forecast of ISCTR at first step

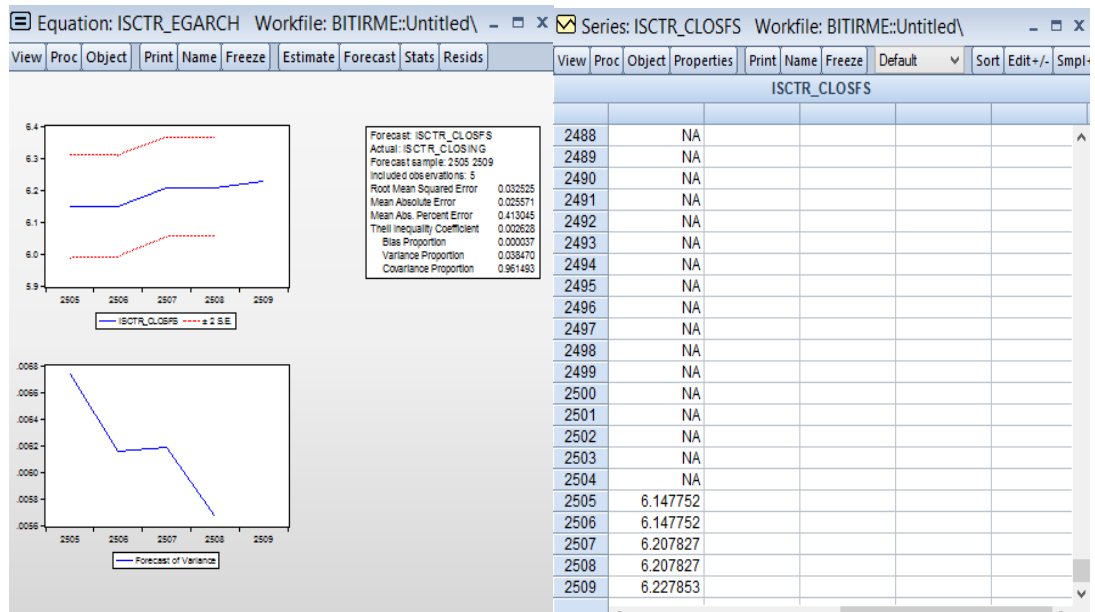


Table 4.49: Forecast Graph of Step 1

Table 4.50: Forecast Values of Step 1

4.4.4.2 Second Step

Forecast

Forecast of
Equation: ISCTR_F1_EGARCH Series: ISCTR_F1

Series names
Forecast name:
S.E. (optional):
GARCH(optional):

Method
☒ Dynamic forecast
☐ Static forecast
☐ Structural (ignore ARMA)
☒ Coef uncertainty in S.E. calc

Forecast sample

Output
☒ Forecast graph
☒ Forecast evaluation

☐ Insert actuals for out-of-sample observations

At the second step, we forecast last 5 terms again after first 5 forecasted terms added end of the first model and modelled again by AR with EGARCH. Our forecast method is dynamic forecast.

Table 4.72: Forecast of ISCTR at second step

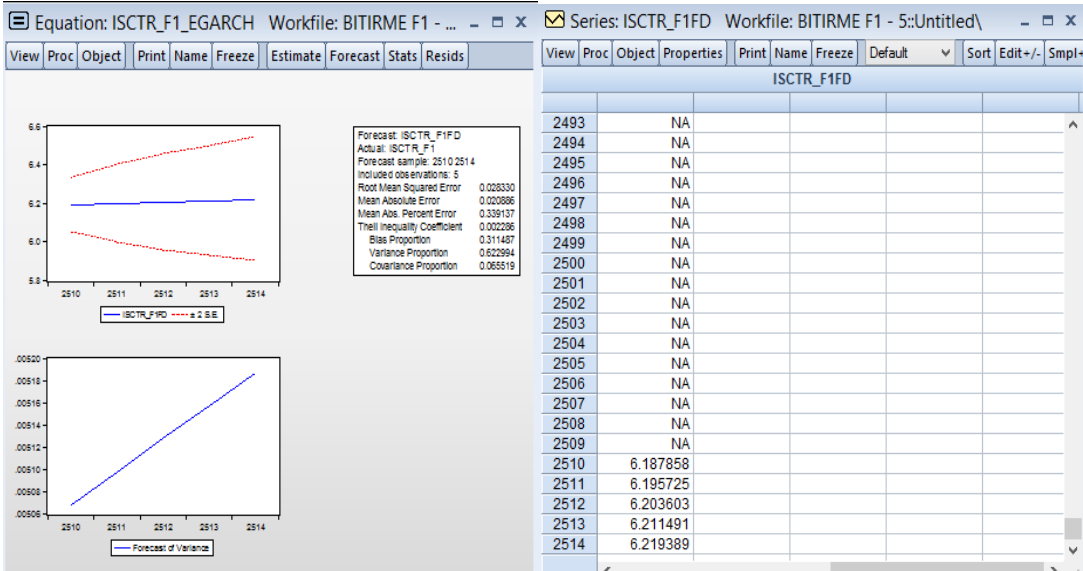


Table 4.51: Forecast Graph of Step 2

Table 4.52: Forecast Values of Step 2

4.4.4.3 Third Step

Forecast

Forecast of
Equation: GARAN_F2_EGARCH Series: GARAN_F2

Series names
Forecast name:
S.E. (optional):
GARCH(optional):

Method
☒ Dynamic forecast
☐ Static forecast
☐ Structural (ignore ARMA)
☒ Coef uncertainty in S.E. calc

Forecast sample

Output
☒ Forecast graph
☒ Forecast evaluation

☐ Insert actuals for out-of-sample observations

OK Cancel

At the Third step, we forecast last 5 terms again after first 5 forecasted terms added end of the first model and modelled again by AR with EGARCH. Our forecast method is dynamic forecast.

Table 4.53: Forecast of ISCTR at third step

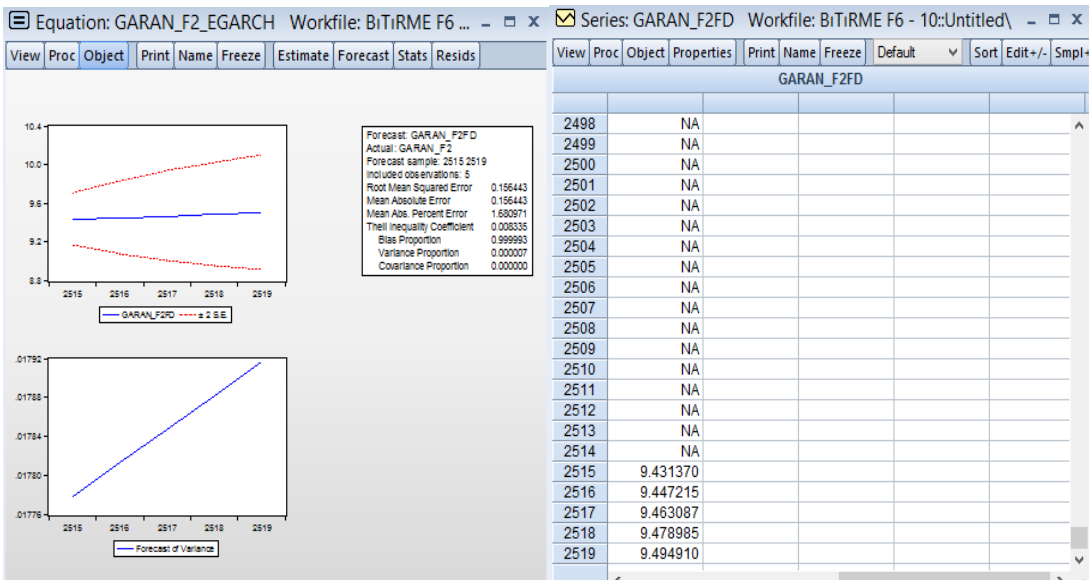


Table 4.54: Forecast Graph of Step 3

Table 4.55: Forecast Values of Step 3

4.4.4.4 Fourth Step

Forecast

Forecast of: Equation: ISCTR_F3_EGARCH Series: ISCTR_F3

Series names
Forecast name: isctr_f3fd
S.E. (optional):
GARCH(optional):

Method
☒ Dynamic forecast
☐ Static forecast
☐ Structural (ignore ARMA)
☒ Coef uncertainty in S.E. calc

Forecast sample
2520 2524

Output
☒ Forecast graph
☒ Forecast evaluation

☐ Insert actuals for out-of-sample observations

OK Cancel

At the Fourth step, we forecast last 5 terms again after first 5 forecasted terms added end of the first model and modelled again by AR with EGARCH. Our forecast method is dynamic forecast.

Table 4.56: Forecast of ISCTR at fourth step

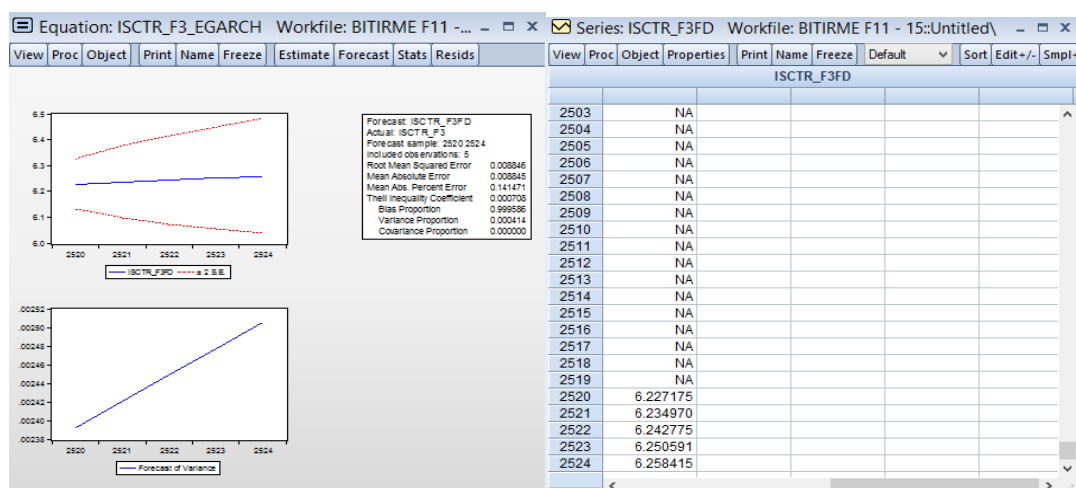


Table 4.57: Forecast Graph of Step 4

Table 4.58: Forecast Values of Step 4

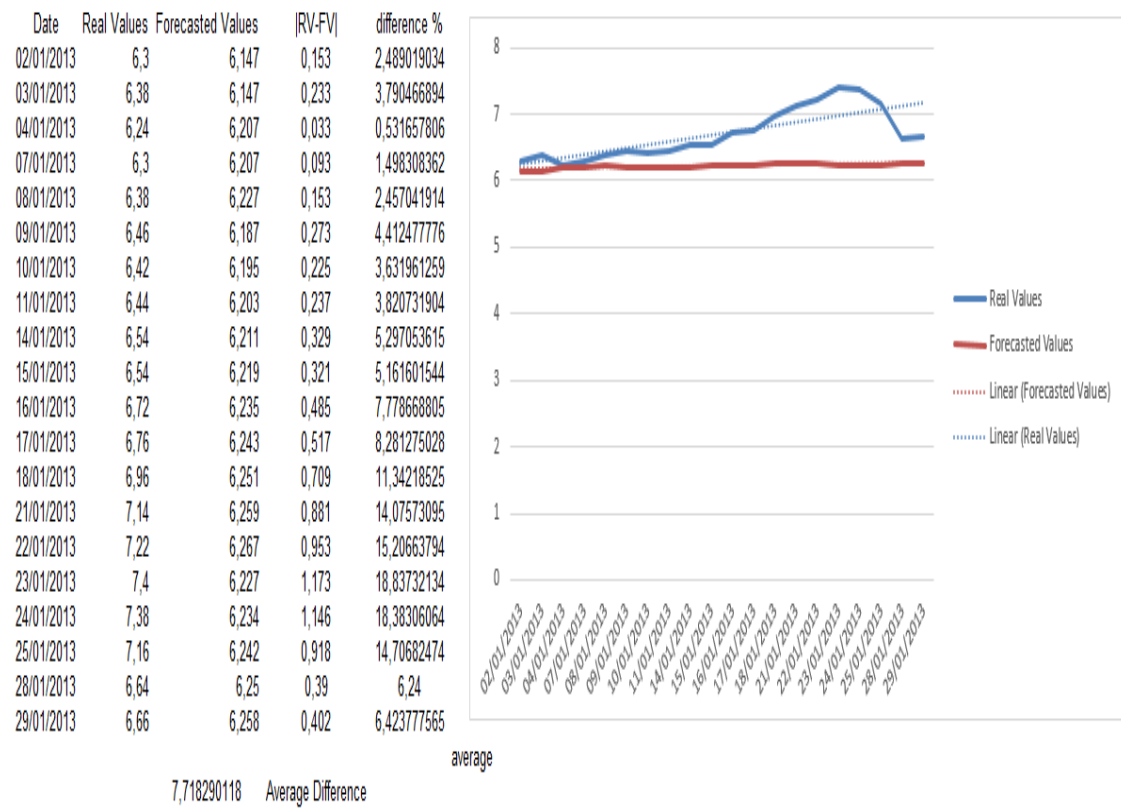


Figure 4.3: Comparison of Real Values and Forecasted Values of ISCTR

Forecast result of ISCTR is very close to real values. The biggest difference is graph of real values is starting upward trend when political choices are changed.

4.4.5. Forecast of YKBNK

Our data will be forecasted step by step in 4 degree. We mentioned that there are two types of forecast. Static forecast and Dynamic Forecast. We use static forecast at the first step. Dynamic forecast is used for the other steps.

4.4.5.1 First Step

At the first step, we forecast last 5 terms in our data which are modelled by AR with EGARCH and our forecast method is static forecast.

Table 4.59: Forecast of YKBNK at first step

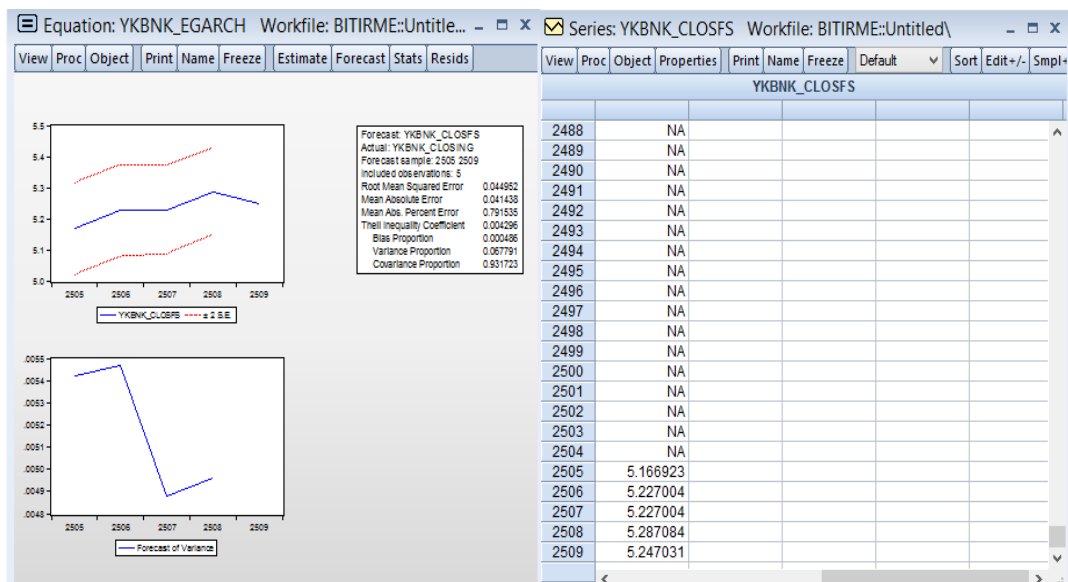


Table 4.60: Forecast Graph of Step 1

Table 4.61: Forecast Values of Step 1

4.4.5.2 Second Step

Forecast

Forecast of: Equation: YKBNK_F1_EGARCH Series: YKBNK_F1

Series names

Forecast name: ykbnk_f1fd
 S.E. (optional):
 GARCH(optional):

Method

☒ Dynamic forecast
☐ Static forecast
☐ Structural (ignore ARMA)
☒ Coef uncertainty in S.E. calc

Forecast sample

2510 2514

Output

☒ Forecast graph
☒ Forecast evaluation

☐ Insert actuals for out-of-sample observations

OK Cancel

At the second step, we forecast last 5 terms again after first 5 forecasted terms added end of the first model and modelled again by AR with EGARCH. Our forecast method is dynamic forecast.

Table 4.62: Forecast of YKBNK at second step

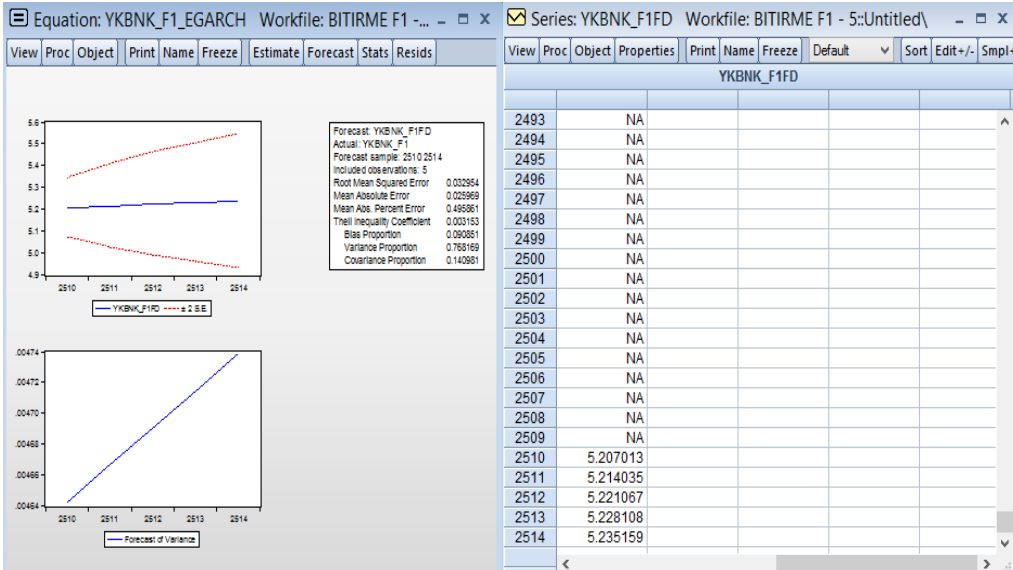


Table 4.63: Forecast Graph of Step 2

Table 4.64: Forecast Values of Step 2

4.4.5.3 Third Step

Forecast

Forecast of
Equation: YKBNK_F2_EGARCH Series: YKBNK_F2

Series names
Forecast name: ykbnk_f2f
S.E. (optional):
GARCH(optional):

Method
☒ Dynamic forecast
☐ Static forecast
☐ Structural (ignore ARMA)
☒ Coef uncertainty in S.E. calc

Forecast sample
2515 2519

Output
☒ Forecast graph
☒ Forecast evaluation

☐ Insert actuals for out-of-sample observations

OK Cancel

At the Third step, we forecast last 5 terms again after first 5 forecasted terms added end of the first model and modelled again by AR with EGARCH. Our forecast method is dynamic forecast.

Table 4.65: Forecast of YKBNK at third step

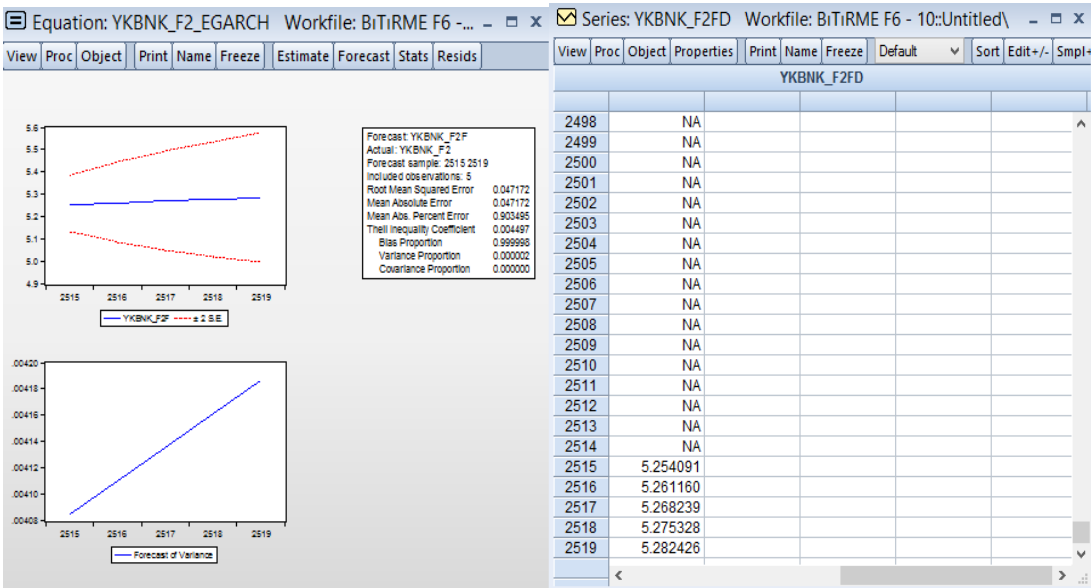


Table 4.66: Forecast Graph of Step 3

Table 4.67: Forecast Graph of Step 3

4.4.5.4 Fourth Step

Forecast

Forecast of
Equation: YKBNK_F3_EGARCH Series: YKBNK_F3

Series names
Forecast name: ykbnk_f3fd
S.E. (optional):
GARCH(optional):

Method
☒ Dynamic forecast
☐ Static forecast
☐ Structural (ignore ARMA)
☒ Coef uncertainty in S.E. calc

Forecast sample
2520 2524

Output
☒ Forecast graph
☒ Forecast evaluation

☐ Insert actuals for out-of-sample observations

OK Cancel

At the Fourth step, we forecast last 5 terms again after first 5 forecasted terms added end of the first model and modelled again by AR with EGARCH. Our forecast method is dynamic forecast.

Table 4.68: Forecast of YKBNK at fourth step

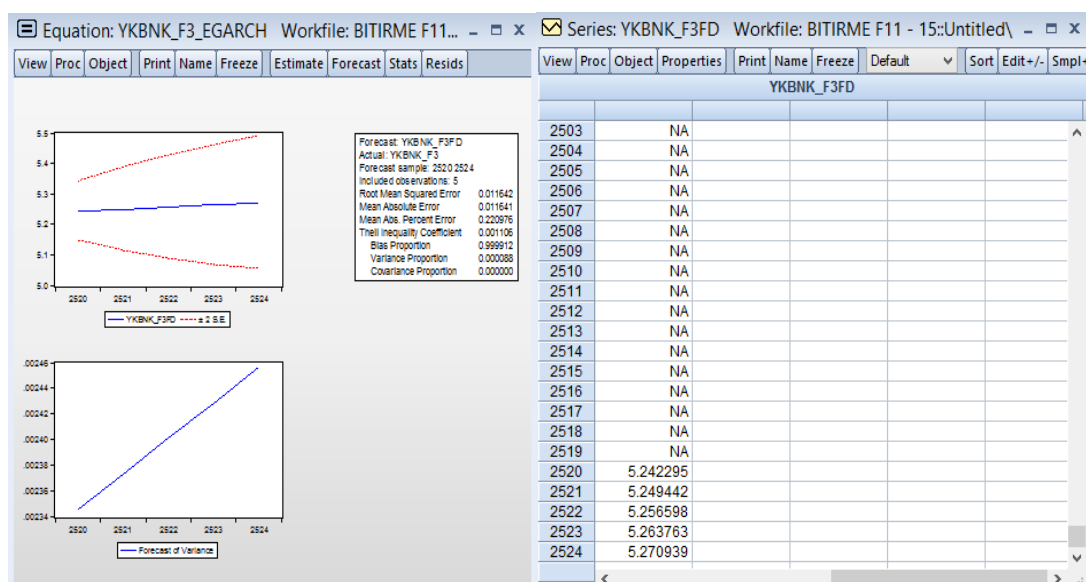


Table 4.69: Forecast Graph of Step 4

Table 4.70: Forecast Values of Step 4

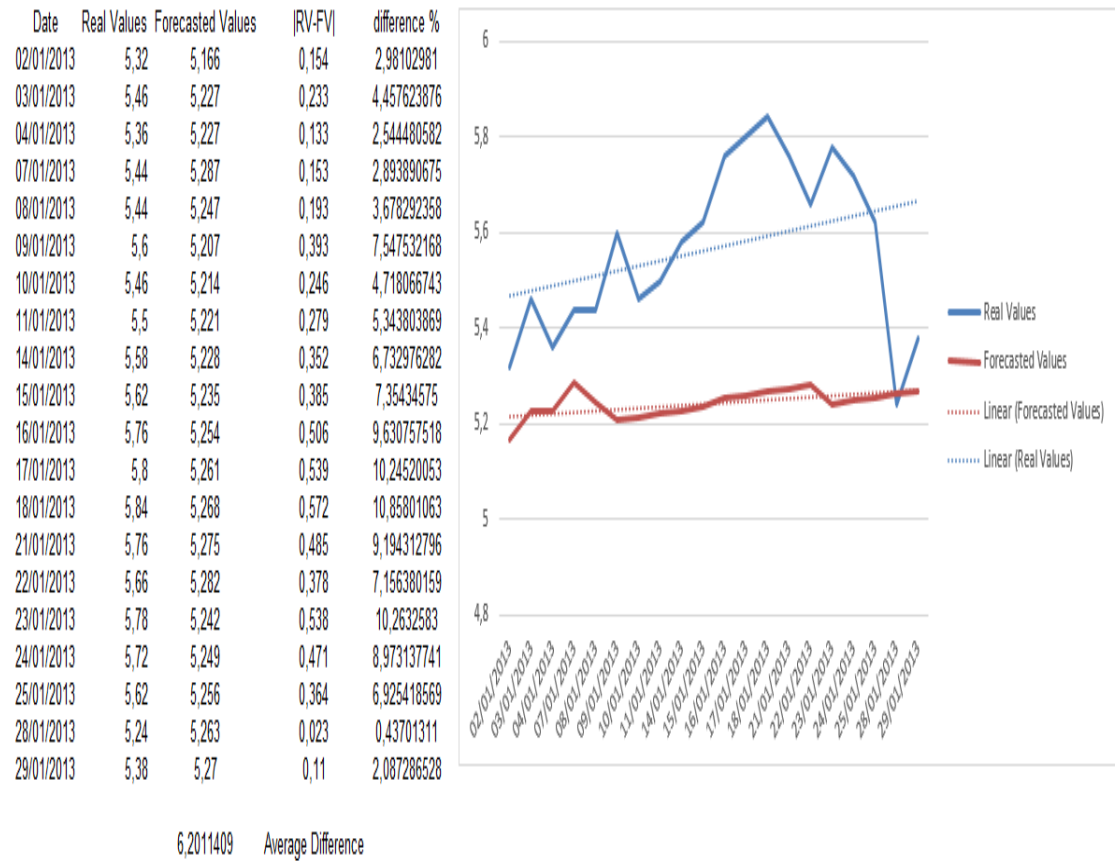


Figure 4.4: Comparison of Real Values and Forecasted Values of YKBNK

Forecast result of YKBNK's trend line and trend line of real values like each other. Cause of the biggest difference between trend lines is political choices were changed at this time interval.

5. CONCLUSION

Forecast applications are one of the most important parts of the decision stages of investment strategies. To estimate future stock prices, proper models and methods must be used in forecast application. In our study, we forecasted 20 days stock prices of four banks in BIST. Then we compared real values and forecasted values of stock prices and calculated error.

In our study, we made tests on our data which are ADF Unit Root Test and comparative GARCH-EGARCH test. Then we used AR Model and EGARCH method according to our test results. We divided our application into 4 steps and used same method and model in every step. In addition to this method we used static forecast in first step and used dynamic forecast in other steps.

Firstly we analyzed the correlogram of the data and consider the lags which are out of the confidence interval. Then we used AR Model to clear lags from autocorrelation and partialcorrelation. In our first data (stock price of AKBANK), we applied GARCH and EGARCH methods separately. EGARCH method gives better results then GARCH method, so we used EGARCH method for all of our data.

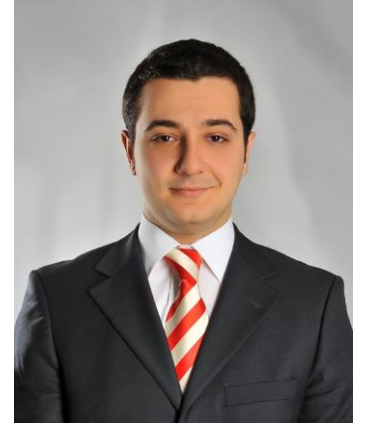
According to our Forecast results, real data and forecasted data acted like each other by a particular error interval.

In conclusion, if we make mathematical approach to forecast results, EGARCH Method is the best method for Forecasting stock price values which contain volatility and they are also financial time series data.

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Mart 2013 – Haziran 2013 (3 Ay) Genel Merkez

Finans Stajı
CarrefourSA Carrefour Sabancı Ticaret Merkezi A.Ş.
Operasyonel Raporlama
Temmuz 2012 - Ağustos 2012 (1 Ay) Genel Müdürlük

Aktüerya Staj Programı
Türkiye Aktüerler Derneği – İstanbul Teknik Üniversitesi İşbirliği
Haziran 2011 – Temmuz 2011 (1 Ay) ITU Fen-Edebiyat Fakültesi

Temel Bankacılık Staj Programı
T.Garanti Bankası A.Ş.
Ağustos 2010 – Eylül 2010 (1 Ay) İhlamurkuyu Şubesi

Bilgisayar Bilgileri:

Microsoft Word 2003, 2007, 2010
Microsoft Excel 2007,2010
Microsoft Power Point
Wolfram Mathematica 7
Lindo
Gams
Matlab
C
SQL
E-Views
Minitab
Spss

Referanslar:

R. Uğur EKMEKÇİOĞLU

Ağaoğlu İnşaat Grubu Muhasebe Müdürü

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Telefon: 0 (216) 655 00 00 E-Posta: Selim_Akyuz@carrefour.com

Özgür GÜNDÜZ

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Telefon: 0 (216) 655 00 00 E-Posta: Ozgur_Gunduz@carrefour.com

Hobiler: Tarih ve ekonomi konulu kitaplar okumak. Basketbol ve masa tenisi oynamak. Yüzmek.Seyahat etmek. Araba kullanmak.

ESRA ÖZTÜRK

Mareşal Çakmak mah. Ortaç cad. No:56/7
Güngören/İSTANBUL
Tel:0535 562 58 76 E-mail: esra_oz15@hotmail.com



Kişisel Bilgiler:

Doğum yeri/tarihi:Bakırköy/ 29.03.1990
Medeni hali:Bekar

Eğitim Durumu:

2008 - 2013	İstanbul Teknik Üniversitesi Matematik Mühendisliği (3.13/4)
02.2012 – 08.2012	Hochschule für Technik Stuttgart (Erasmus)
2004 – 2008	Adnan Menderes Anadolu Lisesi
1996 – 2004	Dr. Refik Saydam İ.Ö.O

Deneyim:

02.13 - ...	Danone – Tikveşli Bütçe Kontrol ve Raporlama Stajyeri
07.11 – 08.11	Grid Telekomünikasyon A.Ş Finans Stajı
06.11 – 07.11	İTÜ Fen – Edebiyat Fakültesi Aktüerya Stajı
07.10 – 08.10	Yapı ve Kredi Bankası Perpa Ticari Şubesi Yaz Stajı

Özellikler:

Yabancı Dil: İngilizce (İleri seviye) , Almanca(Başlangıç)
Bilgisayar: Windows Office Uygulamaları, SQL, E-views
Topluluklar: Bir yıllık Matematik ve Bilgisayar Kulübü aktif üyesi